

# Deciding pure program equivalence with sums and the empty type

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## Question

When are two program fragments  $t$ ,  $u$  contextually equivalent?

$$\forall C, \quad C[t] \approx C[u]$$

Specifics depend on the programming language: input/output, non-termination, just values?

Untyped  $\lambda$ -calculus: undecidable.

Simple type system  $\Lambda C(\alpha, \rightarrow)$ : decidable.

Polymorphism  $\Lambda C(\alpha, \rightarrow, \forall)$ , dependent types  $\Lambda C(\alpha, \rightarrow, \Pi)$ : undecidable.

What's in the middle? Simple types, but richer datatypes?

# History

Decidability of equivalence:

- $\Lambda C(\alpha, \rightarrow)$ : Tait, 1967 or earlier.
- $\Lambda C(\alpha, \rightarrow, \times)$ : essentially the same proof.
- $\Lambda C(\alpha, \rightarrow, \times, 1)$ : essentially the same proof.
- $\Lambda C(\alpha, \rightarrow, \times, 1, +)$ : Ghani, 1995; Altenkirch, Dybjer, Hoffman, Scott: 2001; Balat, Di Cosmo, Fiore: 2004.
- $\Lambda C(\alpha, \rightarrow, \times, 1, +, 0)$ : ? (this work)

Why are  $(+, 0)$  so hard?

# Section 1

## Background

## Simply-typed lambda-calculus

$$\frac{\Gamma, x : A \vdash t : B}{\Gamma \vdash \lambda x. t : A \rightarrow B}$$

$$\frac{\Gamma \vdash t : A \rightarrow B \quad \Gamma \vdash u : A}{\Gamma \vdash t u : B}$$

$$\frac{\Gamma \vdash t_1 : A_1 \quad \Gamma \vdash t_2 : A_2}{\Gamma \vdash (t_1, t_2) : A_1 \times A_2}$$

$$\frac{\Gamma \vdash t : A_1 \times A_2}{\Gamma \vdash \pi_i t : A_i}$$

$$\frac{\Gamma \vdash t : A_i}{\Gamma \vdash \sigma_i t : A_1 + A_2}$$

$$\frac{\Gamma \vdash t : A_1 + A_2 \quad \begin{array}{l} \Gamma, x_1 : A_1 \vdash u_1 : C \\ \Gamma, x_2 : A_2 \vdash u_2 : C \end{array}}{\Gamma \vdash \text{match } t \text{ with } \left. \begin{array}{l} \sigma_1 x_1 \rightarrow u_1 \\ \sigma_2 x_2 \rightarrow u_2 \end{array} \right\} : C}$$

$$\frac{}{\Gamma \vdash () : 1}$$

$$\frac{(x : A) \in \Gamma}{\Gamma \vdash x : A}$$

$$\frac{\Gamma \vdash t : 0}{\Gamma \vdash \text{absurd}(t) : A}$$

## Simply-typed $\beta\eta$ -equivalence; Why is it difficult?

$$(\lambda x. t) u \triangleright_{\beta} t[u/x] \qquad \pi_i (t_1, t_2) \triangleright_{\beta} t_i$$

$$\text{match } \sigma_i t \text{ with } \left| \begin{array}{l} \sigma_1 x_1 \rightarrow u_1 \\ \sigma_2 x_2 \rightarrow u_2 \end{array} \right. \triangleright_{\beta} u_i[t/x_i]$$

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$\beta\eta$ -equivalence is a **syntactic** equivalence: inference judgments that rewrite term fragments.

contextual equivalence is more **semantic**: based on interaction with the outside.

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They coincide in simple type systems (no polymorphism)

Note: two terms  $t, u$  at judgment  $\Gamma \vdash A$  with some type variables  $\alpha, \beta \dots$  are semantically equal if they are contextually equal for **any** instantiation of the  $\alpha, \beta \dots$  by closed types. Consider:

$$x : \alpha, y : \alpha \vdash x \stackrel{?}{\approx}_{\text{ctx}} y : \alpha$$

## Existing approaches (1): rewriting

Neil Ghani; Sam Lindley

Move case-splits  $\left. \begin{array}{l} \text{match } t \text{ with} \\ \sigma_1 x \rightarrow \dots \\ \sigma_2 x \rightarrow \dots \end{array} \right\}$  up in the term.

$$t \left( \begin{array}{l} \text{match } u \text{ with} \\ \sigma_1 x \rightarrow r_1 \\ \sigma_2 x \rightarrow r_2 \end{array} \right) \triangleright \left( \begin{array}{l} \text{match } u \text{ with} \\ \sigma_1 x \rightarrow t r_1 \\ \sigma_2 x \rightarrow t r_2 \end{array} \right)$$

(unlock redexes)

Cases are blocked by scoping:  $\lambda x. \text{match } x \text{ with } \dots$

Then permute/merge/delete cases locally.

## Existing approaches (2): delimited control

Vincent Balat, Roberti Di Cosmo, Marcelo Fiore

Idea: when we encounter a sub-term of positive type, we **go back in time**.

$\lambda x. \dots (\lambda y. \dots (\lambda z. \dots \text{match } x \text{ with } \dots))$

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$\lambda x. \dots (\lambda y. \dots (\lambda z. \dots \text{match } x \text{ y with } \dots))$

as if we had be given

$\lambda x. \dots (\lambda y. \text{match } x \text{ y with } \left. \begin{array}{l} \sigma_1 x' \rightarrow \dots (\lambda z. \dots \text{match } \sigma_1 x' \text{ with } \dots) \\ \sigma_2 x' \rightarrow \dots (\lambda z. \dots \text{match } \sigma_2 x' \text{ with } \dots) \end{array} \right) )$

## Existing approaches (3): categorical magic

Thorsten Altenkirch, Peter Dybjer, Martin Hofmann, Philip Scott

Normalization by Evaluation... in a very carefully defined semantic domains (sheaves).

(What does it actually do on terms?)

(NbE on terms have a nice explanation for just booleans in Thorsten Altenkirch, Tarmo Utsalu. See then Arbob Ahmad, Daniel Licata, Robert Harper.)

## Section 2

### High-level view

## Question

What is a **canonical form** for equivalence of simply-typed terms?

Redundancy: two (syntactically) distinct terms that are equivalent.

Canonical representation: a syntax of programs with no redundancy:

$$(\approx_{\text{stx}}) \implies (\approx_{\text{ctx}})$$



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Normal form (for reduction)  $\neq$  Canonical form (for equivalence)

(see also Watkins, Cervesato, Pfenning, Walker, 2002)

## Idea

Curry-Howard, again: programs as proofs.

The structure of

canonical forms

corresponds to the structure of

proof **search**

Restricting the search space restricts expression redundancy.

## Proof search: Focusing

(existing work)

Gives a term representation ( $\vdash_{\text{foc}}$ ).

Canonical for **effectful** programs.

(Noam Zeilberger's thesis, 2009)

Not canonical for pure programs (stronger equivalences).

Complete: any term can be focused.

$$\Gamma \vdash A \quad \Longrightarrow \quad \Gamma \vdash_{\text{foc}} A$$

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$$\begin{array}{ccc} \Gamma \vdash A & \implies & \Gamma \vdash_{\text{foc}} A \\ \Gamma \vdash t : A & \implies & \exists v \approx_{\beta\eta} t, \quad \Gamma \vdash_{\text{foc}} v : A \end{array}$$

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Remark:  $(\approx_{\beta\eta}) \subseteq (\approx_{\text{ctx}})$

## Proof search: Saturation

(my contribution, 2015).

Family of representations ( $\vdash_{\text{sat}:\Phi}$ ).

Canonical for **pure** programs (this work).

Locally complete: for any finite set of terms, there is a  $\Phi$  such that ( $\vdash_{\text{sat}:\Phi}$ ) is complete.

Extends to the empty type (this work).



## Equivalence algorithm

$\Gamma \vdash t_1, t_2 : A$

# Equivalence algorithm

**Completeness** of focusing:

$$\Gamma \vdash t_1, t_2 : A \quad \rightsquigarrow$$

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## Equivalence algorithm

**Completeness** of focusing:

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**Local completeness** of saturation: pick  $\Phi$  complete for  $\{v_1, v_2\}$ ,

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**Canonicity** of saturated focused forms:

Check syntactic equality of  $w_1, w_2$ :

$$w_1 \not\approx_{\text{stx}} w_2 \quad \Longrightarrow \quad w_1 \not\approx_{\text{ctx}} w_2$$



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Corollary:  $(\not\approx_{\beta\eta}) \subseteq (\not\approx_{\text{ctx}})$ ,

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Check syntactic equality of  $w_1, w_2$ :

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Corollary:  $(\approx_{\beta\eta}) \subseteq (\approx_{\text{ctx}})$ , so  $(\approx_{\beta\eta})$  and  $(\approx_{\text{ctx}})$  coincide.

## Section 3

### Focusing

Unique inhabitant? Enumerate canonical representations

We turn to logic: Logicians use canonicity to reduce the search space

$$\frac{\Gamma \vdash \underline{A} \quad \Gamma, \underline{B} \vdash C}{\Gamma, \underline{A \rightarrow B} \vdash C} -$$

$$\frac{\Gamma, A \vdash B}{\Gamma \vdash A \rightarrow B}$$

$$\frac{\Gamma, \underline{A_i} \vdash C}{\Gamma, \underline{A_1 \times A_2} \vdash C} -$$

$$\frac{\Gamma \vdash A_1 \quad \Gamma \vdash A_2}{\Gamma \vdash A_1 \times A_2}$$

$$\frac{\Gamma, A_1 \vdash C \quad \Gamma, A_2 \vdash C}{\Gamma, A_1 + A_2 \vdash C}$$

$$\frac{\Gamma \vdash \underline{A_i}}{\Gamma \vdash \underline{A_1 + A_2}} +$$

$$\overline{\Gamma, 0 \vdash C} +$$

$$\overline{\Gamma \vdash 1} -$$

Invertible vs. non-invertible rules. Positives vs. negatives.

$$\frac{\Gamma \vdash \underline{A} \quad \Gamma, \underline{B} \vdash C}{\Gamma, \underline{A \rightarrow B} \vdash C} -$$

$$\frac{\Gamma, A \vdash B}{\Gamma \vdash A \rightarrow B}$$

$$\frac{\Gamma, \underline{A_i} \vdash C}{\Gamma, \underline{A_1 \times A_2} \vdash C} -$$

$$\frac{\Gamma \vdash A_1 \quad \Gamma \vdash A_2}{\Gamma \vdash A_1 \times A_2}$$

$$\frac{\Gamma, A_1 \vdash C \quad \Gamma, A_2 \vdash C}{\Gamma, A_1 + A_2 \vdash C}$$

$$\frac{\Gamma \vdash \underline{A_i}}{\Gamma \vdash \underline{A_1 + A_2}} +$$

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$$\overline{\Gamma \vdash 1} -$$

Invertible vs. non-invertible rules. Positives vs. negatives.

$$N, M ::= A \rightarrow B \mid A \times B \mid 1 \quad P, Q ::= A + B \mid 0$$

$$A, B ::= P \mid N \mid \alpha \quad P_a, Q_a ::= P \mid \alpha \quad N_a, M_a ::= N \mid \alpha$$

## Invertible phase

$$\frac{\frac{?}{\alpha + \beta \vdash \alpha}}{\alpha + \beta \vdash \beta + \alpha}$$

If applied too early, non-invertible rules can ruin your proof.

### Focusing restriction 1: invertible phases

Invertible rules must be applied as soon and as long as possible  
– and their order does not matter.

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### Focusing restriction 1: invertible phases

Invertible rules must be applied as soon and as long as possible  
– and their order does not matter.

Imposing this restriction gives a single proof of  $(\alpha \rightarrow \beta) \rightarrow (\alpha \rightarrow \beta)$   
instead of two ( $\lambda f. f$  and  $\lambda f. \lambda x. f x$ ).

After all invertible rules, negative context  $\Gamma_{na}$ , positive goal  $P_a$ .



## Non-invertible phases

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Only step forward: select a formula, apply some non-invertible rule on it.

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When a principal formula is selected for non-invertible rule, they should be applied as long as possible – until its polarity changes.

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### Focusing restriction 2: non-invertible phase

When a principal formula is selected for non-invertible rule, they should be applied as long as possible – until its polarity changes.

Completeness: this restriction preserves provability. **Non-trivial !**

Example of removed redundancy:

$$\frac{\frac{\frac{\alpha_2, \quad \beta_1 \vdash A}{\alpha_2 \times \alpha_3, \quad \beta_1 \vdash A}}{\alpha_2 \times \alpha_3, \quad \beta_1 \times \beta_2 \vdash A}}{\alpha_1 \times \alpha_2 \times \alpha_3, \beta_1 \times \beta_2 \vdash A}}$$

This was focusing:

- invertible as long as a rule matches, until  $\Gamma_{na} \vdash P_a$
- then pick a formula
- then non-invertible as long as a rule matches, until polarity change

Completeness:

$$\Gamma \vdash A \quad \Longrightarrow \quad \Gamma \vdash_{\text{foc}} A$$

## Section 4

# Focused $\lambda$ -calculus

## $\beta$ -normal forms (negative)

$\beta$ -short normal forms:

$$\pi_1 (t, u) = t$$

$$v, w ::= \lambda x. v \mid (v, w) \mid n$$

$$n, m ::= \pi_i n \mid n v \mid x$$

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$\beta$ -short  $\eta$ -long:

$$(y : \alpha \rightarrow \beta) = \lambda x : \alpha. (y x : \beta)$$

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$$v, w ::= \lambda x. v \mid (v, w) \mid (n : \alpha)$$

$$n, m ::= \pi_i n \mid n v \mid x$$



## What about sums?

$$\begin{aligned}v, w &::= \lambda x. v \mid (v, w) \mid \sigma_i v \mid (n : \alpha) \\n, m &::= \pi_i n \mid n v \mid \left( \text{match } n \text{ with} \left| \begin{array}{l} \sigma_1 y_1 \rightarrow v_1 \\ \sigma_2 y_2 \rightarrow v_2 \end{array} \right. \right) \mid x\end{aligned}$$

Does not work:

$$\left( \begin{array}{l} \text{match } n \text{ with} \\ \left| \begin{array}{l} \sigma_1 y_1 \rightarrow \lambda z. v_1 \\ \sigma_2 y_2 \rightarrow \lambda z. v_2 \end{array} \right. \end{array} \right) v \qquad \begin{array}{l} \text{match } n \text{ with} \\ \left| \begin{array}{l} \sigma_1 x \rightarrow \sigma_2 x \\ \sigma_2 x \rightarrow \sigma_1 x \end{array} \right. \end{array}$$

## Focusing to the rescue

$$\begin{aligned}v, w &::= \lambda x. v \mid (v, w) \mid (n : \alpha) \\n, m &::= \pi_i n \mid n v \mid x\end{aligned}$$

$$\begin{aligned}v, w &::= \lambda x. v \mid (v, w) \mid () \\&\quad \mid \text{absurd}(x) \mid \left( \text{match } x \text{ with } \left. \begin{array}{l} \sigma_1 y_1 \rightarrow v_1 \\ \sigma_2 y_2 \rightarrow v_2 \end{array} \right) \right) \\&\quad \mid (\Gamma_{\text{na}} \vdash f : P_a) \\n, m &::= \pi_i n \mid n p \mid x \\p, q &::= \sigma_i p \mid (v : N_a) \\f &::= (n : \alpha) \mid (p : P) \mid \text{let } x = (n : P) \text{ in } v\end{aligned}$$

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Remark: “broken neutrals” are gone

$$\pi_1 \left( \text{match } x \text{ with } \left. \begin{array}{l} \sigma_1 y \rightarrow n_1 \\ \sigma_2 y \rightarrow n_2 \end{array} \right) \right)$$

## Completeness of focusing

Logic:

$$\Gamma \vdash A \quad \Longrightarrow \quad \Gamma \vdash_{\text{foc}} A$$

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Logic:

$$\Gamma \vdash A \quad \Longrightarrow \quad \Gamma \vdash_{\text{foc}} A$$

Programming:

$$\Gamma \vdash t : A \quad \Longrightarrow \quad \exists v, \begin{array}{l} \Gamma \vdash_{\text{foc}} v : A \\ v \approx_{\beta\eta} t \end{array}$$

# Canonicity

Focused normal forms are canonical for the impure  $\lambda$ -calculus.

Proof in Noam Zeilberger's thesis (2009), using ideas from ludics.

## Section 5

# Saturation

# Nope !

Focusing is still not canonical – for pure languages.

`let x = n in C [let x' = n' in v]`

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We want the `let  $x = n$`  to be “as early as possible” – maximal multi-focusing. “Split neutrals early”.

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We want the  $\text{let } x = n$  to be “as early as possible” – maximal multi-focusing. “Split neutrals early”.

Is  $v \approx_{\beta\eta} w$ ? Pull the let-bindings to the roots and compare. Works for sums.

## PhD topic strikes back

I wanted to **enumerate** the canonical inhabitants at a given type.

No existing term to start with.

**Saturation:** split on **all** possible neutrals.

## Saturated focused $\lambda$ -terms

$$\begin{aligned} v, w &::= \lambda x. v \mid (v, w) \mid () \\ &\quad \mid () \mid \text{absurd}(x) \mid \left( \text{match } x \text{ with } \left\{ \begin{array}{l} \sigma_1 y_1 \rightarrow v_1 \\ \sigma_2 y_2 \rightarrow v_2 \end{array} \right. \right) \\ &\quad \mid (\Gamma_{\text{na}} \vdash f : P_a) \\ n, m &::= \pi_i n \mid n p \mid x \\ p, q &::= \sigma_i p \mid (v : N_a) \\ f &::= \text{let } \bar{x} = \bar{n} \text{ in } v \mid (n : \alpha) \mid (p : P) \end{aligned}$$

Plus side-condition on the  $\text{let } \bar{x} = \bar{n}$ :

- they are a set (no duplicates)
- **freshness**: must use a variable of the preceding invertible phase  $v$
- **saturation**:  $n \mid p$  can only be chosen if no fresh variable

(See the paper for their (simple) formal expression.)

## Selection

Which  $\bar{n}$  to split in a given context  $\Gamma$ ?

“All of them”  $\implies$  infinite set  $(x : \mathbb{N} \rightarrow P \vdash \dots)$

Parameter: a **selection function**  $\Phi(\Gamma)$  returning the (finite)  $\bar{n}$ .

(For unicity: “at most two at each type”)

**Local** completeness:

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**Local** completeness:

$$(\Gamma \vdash_{\text{foc}} v : A) \implies \exists \Phi, v', \Gamma \vdash_{\text{sat}:\Phi} v' : A \\ v \approx_{\beta\eta} v'$$

Idea:  $\Phi(\Gamma) \supseteq \{\Gamma \vdash_{\text{foc}} n : P \mid n \in v\}$  suffices.

$\Phi \cup \Phi' \implies$  complete for finite sets of terms.

## Empty type?

$$f : 1 \rightarrow \beta, g : \beta \rightarrow 0, x : \alpha, y : \alpha \vdash ? : \alpha$$

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$$f : 1 \rightarrow \beta, g : \beta \rightarrow 0, x : \alpha, y : \alpha \vdash ? : \alpha$$

$x, y$  would be bad saturated terms.

Additional condition on  $\Phi$ :

$$(\exists n, \Gamma \vdash_{\text{foc}} n : P) \quad \Longrightarrow \quad (\exists n \in \Phi(\Gamma), \Gamma \vdash_{\text{foc}} n : P)$$

Idea: set of those  $P$  is finite – subformula property.

Idea: complete for provability.



# Canonicity

$$\Gamma \vdash_{\text{sat}:\Phi} v, w : A$$
$$v \approx_{\alpha} w$$

$\implies$

$$v \approx_{\text{ctx}} w$$

(The hard part.)

# Canonicity

$$\begin{array}{l} \Gamma \vdash_{\text{sat}:\Phi} v, w : A \\ v \approx_{\alpha} w \end{array} \quad \Longrightarrow \quad v \approx_{\text{ctx}} w$$

(The hard part.)

Corollary:  $(\approx_{\beta\eta}) = (\approx_{\text{ctx}})$

## Canonicity: example

$$n : (1 + \alpha) \rightarrow \alpha \vdash n(\sigma_1()), n(\sigma_2(n\sigma_1())) : \alpha$$

Saturated forms:

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Saturated forms:

$$n : (1 + \alpha) \rightarrow \alpha \vdash \quad ? \quad \not\sim_{\text{stx}} \quad : \alpha$$

?

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$$n : (1 + \alpha) \rightarrow \alpha \vdash n(\sigma_1 ()), n(\sigma_2 (n \sigma_1 ())) : \alpha$$

Saturated forms:

$$n : (1 + \alpha) \rightarrow \alpha \vdash \begin{array}{l} \text{let } z = n(\sigma_1 ()) \text{ in} \\ ? \end{array} \not\sim_{\text{stx}} \begin{array}{l} \text{let } z = n(\sigma_1 ()) \text{ in} \\ ? \end{array} : \alpha$$

## Canonicity: example

$$n : (1 + \alpha) \rightarrow \alpha \vdash n(\sigma_1()), n(\sigma_2(n\sigma_1())) : \alpha$$

Saturated forms:

$$n : (1 + \alpha) \rightarrow \alpha \vdash \begin{array}{l} \text{let } z = n(\sigma_1()) \text{ in} \\ ? \end{array} \not\sim_{\text{stx}} \begin{array}{l} \text{let } z = n(\sigma_1()) \text{ in} \\ ? \end{array} : \alpha$$

## Canonicity: example

$$n : (1 + \alpha) \rightarrow \alpha \vdash n(\sigma_1 ()), n(\sigma_2 (n \sigma_1 ())) : \alpha$$

Saturated forms:

$$\begin{array}{l} \text{let } z = n(\sigma_1 ()) \text{ in} \\ \quad ? \\ n : (1 + \alpha) \rightarrow \alpha \vdash \quad \quad \quad \not\sim_{\text{stx}} \quad \quad \quad : \alpha \\ \text{let } z = n(\sigma_1 ()) \text{ in} \\ \quad ? \end{array}$$



## Canonicity: example

$$n : (1 + \alpha) \rightarrow \alpha \vdash n(\sigma_1 ()), n(\sigma_2 (n \sigma_1 ())) : \alpha$$

Saturated forms:

$$n : (1 + \alpha) \rightarrow \alpha \vdash \begin{array}{l} \text{let } z = n(\sigma_1 ()) \text{ in} \\ \quad \text{let } o = n(\sigma_2 z) \text{ in ?} \\ \quad \quad \quad \not\sim_{\text{stx}} \\ \text{let } z = n(\sigma_1 ()) \text{ in} \\ \quad \text{let } o = n(\sigma_2 z) \text{ in ?} \end{array} : \alpha$$

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Saturated forms:

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Shared context.

## Canonicity: example

$$n : (1 + \alpha) \rightarrow \alpha \vdash n(\sigma_1 ()), n(\sigma_2 (n \sigma_1 ())) : \alpha$$

Saturated forms:

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Shared context. Source of inequality:

## Canonicity: example

$$n : (1 + \alpha) \rightarrow \alpha \vdash n(\sigma_1()), n(\sigma_2(n\sigma_1())) : \alpha$$

Saturated forms:

$$n : (1 + \alpha) \rightarrow \alpha \vdash \begin{array}{l} \text{let } z = n(\sigma_1()) \text{ in} \\ \quad \text{let } o = n(\sigma_2 z) \text{ in } z \\ \qquad \qquad \qquad \not\sim_{\text{stx}} \\ \text{let } z = n(\sigma_1()) \text{ in} \\ \quad \text{let } o = n(\sigma_2 z) \text{ in } o \end{array} : \alpha$$

Shared context. Source of inequality:  $z \not\sim_{\text{stx}} o$ .

## Canonicity: example

$$n : (1 + \alpha) \rightarrow \alpha \vdash n(\sigma_1()), n(\sigma_2(n\sigma_1())) : \alpha$$

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Shared context. Source of inequality:  $z \not\sim_{\text{stx}} o$ .

## Canonicity: example

$$n : (1 + \alpha) \rightarrow \alpha \vdash n(\sigma_1 ()), n(\sigma_2 (n \sigma_1 ())) : \alpha$$

Saturated forms:

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Shared context. Source of inequality:  $z \not\approx_{\text{stx}} o$ .

Type variables:

## Canonicity: example

$$n : (1 + \alpha) \rightarrow \alpha \vdash n(\sigma_1 ()), n(\sigma_2 (n \sigma_1 ())) : \alpha$$

Saturated forms:

$$n : (1 + \alpha) \rightarrow \alpha \vdash \begin{array}{l} \text{let } z = n(\sigma_1 ()) \text{ in} \\ \quad \text{let } o = n(\sigma_2 z) \text{ in } z \\ \qquad \qquad \qquad \not\approx_{\text{stx}} \qquad \qquad \qquad : \alpha \\ \text{let } z = n(\sigma_1 ()) \text{ in} \\ \quad \text{let } o = n(\sigma_2 z) \text{ in } o \end{array}$$

Shared context. Source of inequality:  $z \not\approx_{\text{stx}} o$ .

Type variables: pick a finite type of codes of the form  $1 + (1 + \dots)$ .

## Canonicity: example

$$n : (1 + \alpha) \rightarrow \alpha \vdash n(\sigma_1 ()), n(\sigma_2 (n \sigma_1 ())) : \alpha$$

Saturated forms:

$$\begin{array}{l} n : (1 + \alpha) \rightarrow \alpha \vdash \\ \quad \text{let } \mathbf{z} = n(\sigma_1 ()) \text{ in} \\ \quad \quad \text{let } \mathbf{o} = n(\sigma_2 z) \text{ in } z \\ \quad \quad \quad \not\sim_{\text{stx}} \\ \quad \text{let } \mathbf{z} = n(\sigma_1 ()) \text{ in} \\ \quad \quad \text{let } \mathbf{o} = n(\sigma_2 z) \text{ in } o \end{array} : \alpha$$

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Here,



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Saturated forms:

$$n : (1 + \alpha) \rightarrow \alpha \vdash \begin{array}{l} \text{let } z = n(\sigma_1()) \text{ in} \\ \quad \text{let } o = n(\sigma_2 z) \text{ in } z \\ \qquad \qquad \qquad \not\approx_{\text{stx}} \qquad \qquad \qquad : \alpha \\ \text{let } z = n(\sigma_1()) \text{ in} \\ \quad \text{let } o = n(\sigma_2 z) \text{ in } o \end{array}$$

Shared context. Source of inequality:  $z \not\approx_{\text{stx}} o$ .

Type variables: pick a finite type of codes of the form  $1 + (1 + \dots)$ .

Here,  $\hat{\alpha} \stackrel{\text{def}}{=} 1 + 1$ ,  $\hat{z} \stackrel{\text{def}}{=} \sigma_1()$  and  $\hat{o} \stackrel{\text{def}}{=} \sigma_2()$ .

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$$n : (1 + \alpha) \rightarrow \alpha \vdash n(\sigma_1()), n(\sigma_2(n\sigma_1())) : \alpha$$

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Separating context:  $C[\square] \stackrel{\text{def}}{=} (\lambda n. \square) \hat{n}$

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$$\hat{n} \stackrel{\text{def}}{=} \left\{ \right.$$

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Saturated forms:

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Separating context:  $C[\square] \stackrel{\text{def}}{=} (\lambda n. \square) \hat{n}$

$$\hat{n} \stackrel{\text{def}}{=} \left\{ \begin{array}{l} \sigma_1() \\ \vdots \end{array} \right. \mapsto$$

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Saturated forms:

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Separating context:  $C[\square] \stackrel{\text{def}}{=} (\lambda n. \square) \hat{n}$

$$\hat{n} \stackrel{\text{def}}{=} \left\{ \begin{array}{l} \sigma_1() \mapsto \hat{z} \\ \sigma_2() \mapsto \hat{o} \end{array} \right.$$

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Separating context:  $C[\square] \stackrel{\text{def}}{=} (\lambda n. \square) \hat{n}$

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## Canonicity: example

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Saturated forms:

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Shared context. Source of inequality:  $z \not\approx_{\text{stx}} o$ .

Type variables: pick a finite type of codes of the form  $1 + (1 + \dots)$ .

Here,  $\hat{\alpha} \stackrel{\text{def}}{=} 1 + 1$ ,  $\hat{z} \stackrel{\text{def}}{=} \sigma_1 ()$  and  $\hat{o} \stackrel{\text{def}}{=} \sigma_2 ()$ .

Separating context:  $C[\square] \stackrel{\text{def}}{=} (\lambda n. \square) \hat{n}$

$$\hat{n} \stackrel{\text{def}}{=} \begin{cases} \sigma_1 () & \mapsto \hat{z} \\ \sigma_2 \hat{z} & \mapsto \hat{o} \end{cases}$$

Thanks

Questions?



negative types  $N, M ::= \alpha^-, \beta^-, \gamma^- \mid P \rightarrow N \mid N_1 \times N_2 \mid 1 \mid \langle P \rangle^-$   
 positive types  $P, Q ::= \alpha^+, \beta^+, \gamma^+ \mid P_1 + P_2 \mid 0 \mid \langle N \rangle^+$

$P_a, Q_a ::= P, Q \mid \alpha^-, \beta^-$      $N_a, M_a ::= N, M \mid \alpha^+, \beta^+$

invertible terms  $t, u, r ::= \lambda x. t \mid () \mid (t_1, t_2) \mid (f : P)$   
 $\mid \text{absurd}(x) \mid \text{match } x \text{ with } (\sigma_i x \rightarrow t_i)^i$

focusing terms  $f, g ::= \text{let } (x : P) = n \text{ in } t \mid (n : \alpha^-) \mid p$

negative neutrals  $n, m ::= (x : N) \mid n p \mid \pi_i n$

positive neutrals  $p, q ::= \sigma_i p \mid (x : \alpha^+)$

shift-or-atom notations  $\langle N \rangle_a^+ \stackrel{\text{def}}{=} \langle N \rangle^+ \quad \langle \alpha^+ \rangle_a^+ \stackrel{\text{def}}{=} \alpha^+$   
 $\langle P \rangle_a^- \stackrel{\text{def}}{=} \langle P \rangle^- \quad \langle \alpha^- \rangle_a^- \stackrel{\text{def}}{=} \alpha^-$

$$\frac{\Gamma_{\text{na}}; \Sigma_{\text{p}}, x : P \vdash_{\text{inv}} t : N \mid \emptyset}{\Gamma_{\text{na}}; \Sigma_{\text{p}} \vdash_{\text{inv}} \lambda x. t : P \rightarrow N \mid \emptyset}$$

$$\frac{(\Gamma_{\text{na}}; \Sigma_{\text{p}} \vdash_{\text{inv}} t_i : N_i \mid \emptyset)^i}{\Gamma_{\text{na}}; \Sigma_{\text{p}} \vdash_{\text{inv}} (t_1, t_2) : N_1 \times N_2 \mid \emptyset}$$

$$\frac{(\Gamma_{\text{na}}; \Sigma_{\text{p}}, x : Q_i \vdash_{\text{inv}} t_i : N \mid P_a)^i}{\Gamma_{\text{na}}; \Sigma_{\text{p}}, x : Q_1 + Q_2 \vdash_{\text{inv}} \text{match } x \text{ with } (\sigma_i x \rightarrow t_i)^i : N \mid P_a}$$

$$\overline{\Gamma_{\text{na}}; \Sigma_{\text{p}}, x : 0 \vdash_{\text{inv}} \text{absurd}(x) : N \mid P_a}$$

$$\overline{\Gamma_{\text{na}}; \Sigma_{\text{p}} \vdash_{\text{inv}} () : 1 \mid \emptyset}$$

$$\frac{\Gamma_{\text{na}}, \Gamma'_{\text{na}} \vdash_{\text{foc}} f : (P_a \mid Q_a)}{\Gamma_{\text{na}}; \langle \Gamma'_{\text{na}} \rangle_a^+ \vdash_{\text{inv}} f : \langle P_a \rangle_a^- \mid Q_a}$$

$$\frac{\Gamma_{\text{na}} \vdash p \uparrow P}{\Gamma_{\text{na}} \vdash_{\text{foc}} p : P}$$

$$\frac{\Gamma_{\text{na}} \vdash n \Downarrow \alpha^-}{\Gamma_{\text{na}} \vdash_{\text{foc}} n : \alpha^-} \quad \frac{\Gamma_{\text{na}} \vdash n \Downarrow \langle P \rangle^- \quad \Gamma_{\text{na}}; x : P \vdash_{\text{inv}} t : \emptyset \mid Q_a}{\Gamma_{\text{na}} \vdash_{\text{foc}} \text{let } x = n \text{ in } t : Q_a}$$

$$\overline{\Gamma_{\text{na}}, x : N \vdash x \Downarrow N}$$

$$\overline{\Gamma_{\text{na}}, x : \alpha^+ \vdash x \uparrow \alpha^+}$$

$$\frac{\Gamma_{\text{na}} \vdash n \Downarrow N_1 \times N_2}{\Gamma_{\text{na}} \vdash \pi_i n \Downarrow N_i}$$

$$\frac{\Gamma_{\text{na}}; \emptyset \vdash_{\text{inv}} t : N \mid \emptyset}{\Gamma_{\text{na}} \vdash t \uparrow \langle N \rangle^+}$$

$$\frac{\Gamma_{\text{na}} \vdash n \Downarrow P \rightarrow N \quad \Gamma_{\text{na}} \vdash p \uparrow P}{\Gamma_{\text{na}} \vdash n p \Downarrow N}$$

$$\frac{\Gamma_{\text{na}} \vdash p \uparrow P_i}{\Gamma_{\text{na}} \vdash \sigma_i p \uparrow P_1 + P_2}$$

$$\frac{\Gamma_{na}; \Sigma_p, x : P \vdash_{\text{sinv}} t : N \mid \emptyset}{\Gamma_{na}; \Sigma_p \vdash_{\text{sinv}} \lambda x. t : P \rightarrow N \mid \emptyset}$$

$$\frac{(\Gamma_{na}; \Sigma_p \vdash_{\text{sinv}} t_i : N_i \mid \emptyset)^i}{\Gamma_{na}; \Sigma_p \vdash_{\text{sinv}} (t_1, t_2) : N_1 \times N_2 \mid \emptyset}$$

$$\overline{\Gamma_{na}; \Sigma_p \vdash_{\text{sinv}} () : 1 \mid \emptyset}$$

$$\overline{\Gamma_{na}; \Sigma_p, x : 0 \vdash_{\text{sinv}} \text{absurd}(x) : N \mid Q_a}$$

$$\frac{(\Gamma_{na}; \Sigma_p, x : P_i \vdash_{\text{sinv}} t_i : N \mid Q_a)^i}{\Gamma_{na}; \Sigma_p, x : P_1 + P_2 \vdash_{\text{sinv}} \text{match } x \text{ with } (\sigma_i x \rightarrow t_i)^i : N \mid Q_a}$$

$$\frac{\Gamma_{na}; \Gamma'_{na} \vdash_{\text{sat}} f : (P_a \mid Q_a)}{\Gamma_{na}; \langle \Gamma'_{na} \rangle_a^+ \vdash_{\text{sinv}} f : \langle P_a \rangle_a^- \mid Q_a}$$

$$\frac{\Gamma_{na} \vdash_s p \uparrow P}{\Gamma_{na}; \emptyset \vdash_{\text{sat}} p : P}$$

$$\frac{\Gamma_{na} \vdash_s n \downarrow \alpha^-}{\Gamma_{na}; \emptyset \vdash_{\text{sat}} n : \alpha^-}$$

$$\frac{(\bar{n}, \bar{P}) \stackrel{\text{def}}{=} \Phi(\Gamma_{na}, \Gamma'_{na}) \left\{ (n, P) \mid \begin{array}{l} (\Gamma_{na}, \Gamma'_{na} \vdash_s n \downarrow \langle P \rangle^-) \\ \wedge \exists x \in \Gamma'_{na}, x \in n \end{array} \right\}}{\Gamma_{na}, \Gamma'_{na}; \bar{x} : \bar{P} \vdash_{\text{sinv}} t : \emptyset \mid Q_a} \quad \Gamma_{na}; \Gamma'_{na} \vdash_{\text{sat}} \text{let } \bar{x} = \bar{n} \text{ in } t : Q_a$$

$(\Gamma_{na} \vdash_s n \downarrow N), (\Gamma_{na} \vdash_s p \uparrow P)$ , as before