

COMA: an intermediate verification language with explicit abstraction barriers

Andrei Paskevich and Paul Patault

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LMF, Université Paris-Saclay • Toccata, Inria Saclay

$$\text{WP}(\text{skip}, \Phi) \triangleq \Phi$$

$$\text{WP}(e ; d, \Phi) \triangleq \text{WP}(e, \text{WP}(d, \Phi))$$

$$\text{WP}(x \leftarrow v, \Phi) \triangleq \Phi[x \mapsto v]$$

$$\text{WP}(\text{if } \varphi \text{ then } e \text{ else } d, \Phi) \triangleq \text{if } \varphi \text{ then } \text{WP}(e, \Phi) \text{ else } \text{WP}(d, \Phi)$$

$$\text{WP}(\text{while } \varphi \text{ do } e \text{ done}, \Phi) \triangleq \exists \psi. \psi \wedge \forall \bar{x}. \psi \rightarrow \text{if } \varphi \text{ then } \text{WP}(e, \psi) \text{ else } \Phi$$

$$\text{WP}(\text{skip}, \Phi, \Psi) \triangleq \Phi$$

$$\text{WP}(e ; d, \Phi, \Psi) \triangleq \text{WP}(e, \text{WP}(d, \Phi, \Psi), \Psi)$$

$$\text{WP}(\text{skip}, \Phi, \Psi) \triangleq \Phi$$

$$\text{WP}(e ; d, \Phi, \Psi) \triangleq \text{WP}(e, \text{WP}(d, \Phi, \Psi), \Psi)$$

$$\text{WP}(\text{raise}, \Phi, \Psi) \triangleq \Psi$$

$$\text{WP}(\text{try } e \text{ with } d, \Phi, \Psi) \triangleq \text{WP}(e, \Phi, \text{WP}(d, \Phi, \Psi))$$

x, y, z

variable

 $s, t ::= x \mid 0 \dots \mid s + t \dots$

term

 $\varphi, \psi ::= s = t \dots \mid \varphi \wedge \psi \dots$

formula

data

x, y, z variable

$s, t ::= x \mid 0 \dots \mid s + t \dots$ term

$\varphi, \psi ::= s = t \dots \mid \varphi \wedge \psi \dots$ formula

data

code

h, g, f handler

$\pi, \rho ::= h \bar{x} \varphi \bar{\pi}$ prototype

x, y, z variable

$s, t ::= x \mid 0 \dots \mid s + t \dots$ term

$\varphi, \psi ::= s = t \dots \mid \varphi \wedge \psi \dots$ formula

data

code

h, g, f handler

$\pi, \rho ::= h \bar{x} \varphi \bar{\pi}$ prototype

$e, d ::= h \bar{s} \bar{g}$ expression

| $e / h \bar{x} \varphi \bar{\pi} = d$

| $e / h \bar{x} \bar{\pi} \rightarrow d$

```

factorial (n: int) { n ≥ 0 }
  (return (m: int) { m = n! })
= fact 1 n
  / fact (r: int) (k: int)
    { 0 ≤ k ≤ n ∧ r · k! = n! }
  = if (k > 0) tt ff
    / tt → fact (r * k) (k - 1)
    / ff → return r

```

user-written code

predefined handlers

```

if (b: bool) (then { b }) (else { ¬b })
halt { ⊤ }
fail { ⊥ }

```


$$\text{WP}(e / h \bar{x} \varphi \bar{\pi} = d) \triangleq \text{WP}(e) \wedge \forall \bar{x}. \varphi \rightarrow \text{WP}(d)$$

$$\text{WP}(e / h \bar{x} \bar{\pi} \rightarrow d) \triangleq \text{WP}(e)$$

$$\text{WP}(e / h \bar{x} \varphi \bar{\pi} = d) \triangleq \text{WP}(e) \wedge \forall \bar{x}. \varphi \rightarrow \text{WP}(d)$$

$$\text{WP}(h_{\bar{x}\bar{\pi} \rightarrow d} \bar{s} \bar{g}) \triangleq \text{WP}(d)[\bar{x} \mapsto \bar{s}] \wedge \bigwedge_{i=1}^n (\pi_i[\bar{x} \mapsto \bar{s}] \blacktriangleright g_i)$$

$$\text{WP}(e / h \bar{x} \bar{\pi} \rightarrow d) \triangleq \text{WP}(e)$$

$$\text{WP}(e / h \bar{x} \varphi \bar{\pi} = d) \triangleq \text{WP}(e) \wedge \forall \bar{x}. \varphi \rightarrow \text{WP}(d)$$

$$\text{WP}(h_{\bar{x}\bar{\pi} \rightarrow d} \bar{s} \bar{g}) \triangleq \text{WP}(d)[\bar{x} \mapsto \bar{s}] \wedge \bigwedge_{i=1}^n (\pi_i[\bar{x} \mapsto \bar{s}] \blacktriangleright g_i)$$

$$\text{WP}(e / h \bar{x} \bar{\pi} \rightarrow d) \triangleq \text{WP}(e)$$

$$\text{WP}(e / h \bar{x} \varphi \bar{\pi} = d) \triangleq \text{WP}(e) \wedge \forall \bar{x}. \varphi \rightarrow \text{WP}(d)$$

$$h \bar{x} \varphi \bar{\pi} \blacktriangleright g \triangleq \forall \bar{x}. \varphi \rightarrow \text{WP}(g \bar{x} \bar{\pi})$$

$$\text{WP}(h_{\bar{x}\varphi\bar{\pi}} \bar{s} \bar{g}) \triangleq \varphi[\bar{x} \mapsto \bar{s}] \wedge \bigwedge_{i=1}^n (\pi_i[\bar{x} \mapsto \bar{s}] \blacktriangleright g_i)$$

$$\text{WP}(h_{\bar{x}\bar{\pi} \rightarrow d} \bar{s} \bar{g}) \triangleq \text{WP}(d)[\bar{x} \mapsto \bar{s}] \wedge \bigwedge_{i=1}^n (\pi_i[\bar{x} \mapsto \bar{s}] \blacktriangleright g_i)$$

$$\text{WP}(e / h \bar{x} \bar{\pi} \rightarrow d) \triangleq \text{WP}(e)$$

$$\text{WP}(e / h \bar{x} \varphi \bar{\pi} = d) \triangleq \text{WP}(e) \wedge \forall \bar{x}. \varphi \rightarrow \text{WP}(d)$$

$$h \bar{x} \varphi \bar{\pi} \blacktriangleright g \triangleq \forall \bar{x}. \varphi \rightarrow \text{WP}(g \bar{x} \bar{\pi})$$

```

factorial (n: int) { n ≥ 0 }
  (return (m: int) { m = n! })
= fact 1 n
  / fact (r: int) (k: int)
    { 0 ≤ k ≤ n ∧ r · k! = n! }
  = if (k > 0) tt ff
    / tt → fact (r * k) (k - 1)
    / ff → return r

```

$$\forall n: \text{int}. n \geq 0 \rightarrow 0 \leq n \leq n \wedge 1 \cdot n! = n! \wedge$$

$$\forall r: \text{int}. \forall k: \text{int}. 0 \leq k \leq n \wedge r \cdot k! = n! \rightarrow$$

$$(k > 0 \rightarrow 0 \leq k - 1 \leq n \wedge r \cdot k \cdot (k - 1)! = n!) \wedge$$

$$(k \leq 0 \rightarrow r = n!)$$

```
type tree = Node tree elt tree
          | Leaf
```

```
let removeRoot (t: tree) : tree
```

```
= match t with
   | Node l _ r → mergeTree l r
   | Leaf → fail
```

```
type tree = Node tree elt tree
          | Leaf
```

```
let removeRoot (t: tree) : tree
  requires { t ≠ Leaf }
  ensures { match t with
            | Node l _ r → ∀e:elt. e ∈ result ↔ e ∈ l ∨ e ∈ r
            | Leaf → false }
= match t with
  | Node l _ r → mergeTree l r
  | Leaf → fail
```



```
type tree = Node tree elt tree
          | Leaf
```

```
removeRoot (Node l _ r)
  ensures {  $\forall e:\text{elt}. e \in \text{result} \leftrightarrow e \in l \vee e \in r$  }
= mergeTree l r
```

```
removeRoot Leaf = fail
```

h, g, f handler

$\pi, \rho ::= h \bar{x} \bar{\pi}$ prototype

$k, o ::= h$ callable
 | $\lambda \bar{x} \bar{\pi} . e$

$e, d ::= k \bar{s} \bar{o}$ expression
 | $e / h \bar{x} \bar{\pi} = d$
 | φe
 | $\uparrow e$

```
factorial (n: int) (return (m: int))
= { n ≥ 0 }
  ↑ fact 1 n
    / fact (r: int) (k: int)
      = { 0 ≤ k ≤ n ∧ r · k! = n! }
        ↑ if (k > 0) (λ. fact (r * k) (k - 1))
              (λ. break r)
          / break (m: int) = { m = n! } ↑ return m
```

```

removeRoot (t: tree) (return (s: tree))
= unTree t (λl: tree. λ_: elt. λr: tree.
    ↑ mergeTree l r out
    / out (s: tree) =
        { ∀e:elt. e ∈ s ↔ e ∈ l ∨ e ∈ r }
    ↑ return s)
fail

```

```
removeRoot (t: tree) (return (s: tree))  
= unTree t (\l: tree. \_: elt. \r: tree.  
           mergeTree l r return)  
fail
```

$C_{\flat}^p(e)$, $C_{\flat}^p(k)$ – verification condition of an expression or a callable

p – should we produce proof obligations at the current position?

\flat – should we produce proof obligations after the barrier \uparrow ?

C_{\perp}^{\top} – **caller VC**, the specification (contract) of a handler

C_{\top}^{\perp} – **callee VC**, implementation respects the contract

C_{\top}^{\top} – **full VC**, prove everything, ignore the barriers

C_{\perp}^{\perp} – **null VC**, prove nothing, ignore the barriers

$$C_{\mathfrak{b}}^{\top}(h) \triangleq h$$

$$C_{\mathfrak{b}}^{\perp}(h) \triangleq \mathfrak{b}h$$

$$\mathfrak{b}\Phi \longrightarrow \Phi[\overline{f \mapsto \mathfrak{b}f}]_{f \in \text{FS}(\Phi)}$$

$$\mathfrak{b}\text{fail} \longrightarrow \top$$

$$C_{\mathfrak{b}}^{\top}(h) \triangleq h \qquad C_{\mathfrak{b}}^{\perp}(h) \triangleq \mathfrak{b}h$$

$$C_{\mathfrak{b}}^{\mathfrak{p}}(\varphi e) \triangleq \text{if } \varphi \text{ then } C_{\mathfrak{b}}^{\mathfrak{p}}(e) \text{ else } C_{\mathfrak{b}}^{\mathfrak{p}}(\text{fail})$$

$$\mathfrak{b}\Phi \longrightarrow \Phi[\overline{f \mapsto \mathfrak{b}f}]_{f \in \text{FS}(\Phi)}$$

$$\mathfrak{b}\text{fail} \longrightarrow \top$$

$$C_{\delta}^{\top}(h) \triangleq h \qquad C_{\delta}^{\perp}(h) \triangleq \text{!}h$$

$$C_{\delta}^{\text{p}}(e / h \bar{x} \bar{\pi} = d) \triangleq \text{let } h = \lambda \bar{x} \bar{\pi}. \quad C_{\perp}^{\top}(d) \\ \text{in } C_{\delta}^{\text{p}}(e) \wedge \forall \bar{x} \bar{\pi}. C_{\text{p}}^{\perp}(d)$$

$$C_{\delta}^{\text{p}}(\varphi e) \triangleq \text{if } \varphi \text{ then } C_{\delta}^{\text{p}}(e) \text{ else } C_{\delta}^{\text{p}}(\text{fail})$$

$$\text{!}\Phi \longrightarrow \Phi[\overline{f \mapsto \text{!}f}]_{f \in \text{FS}(\Phi)}$$

$$\text{!fail} \longrightarrow \top$$

$$C_{\mathfrak{b}}^{\top}(h) \triangleq h \qquad C_{\mathfrak{b}}^{\perp}(h) \triangleq \mathfrak{b}h$$

$$C_{\mathfrak{b}}^{\mathfrak{p}}(e / h \bar{x} \bar{\pi} = d) \triangleq \text{let } h = \lambda \bar{x} \bar{\pi}. \forall h. C_{\perp}^{\top}(d) \\ \text{in } C_{\mathfrak{b}}^{\mathfrak{p}}(e) \wedge \forall \bar{x} \bar{\pi}. C_{\mathfrak{p}}^{\perp}(d)$$

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$$\mathfrak{b}\Phi \longrightarrow \Phi[\overline{f \mapsto \mathfrak{b}f}]_{f \in \text{FS}(\Phi)}$$

$$\mathfrak{b}\text{fail} \longrightarrow \top$$

$$\forall h_{\bar{x} \bar{\pi}}. \Phi \triangleq \text{let } h = \lambda \bar{x} \bar{\pi}. \text{fail} \wedge \bigwedge_{g_{\bar{z} \bar{\rho}} \in \bar{\pi}} \forall \bar{z} \bar{\rho}. g \bar{z} \bar{\rho} \text{ in } \Phi$$

$$C_{\mathfrak{b}}^{\top}(h) \triangleq h \qquad C_{\mathfrak{b}}^{\perp}(h) \triangleq \mathfrak{b}h$$

$$C_{\mathfrak{b}}^{\mathfrak{p}}(e / h \bar{x} \bar{\pi} = d) \triangleq \mathbf{let} \ h = \lambda \bar{x} \bar{\pi}. \forall h. C_{\perp}^{\top}(d) \\ \mathbf{in} \ C_{\mathfrak{b}}^{\mathfrak{p}}(e) \wedge \forall \bar{x} \bar{\pi}. C_{\mathfrak{p}}^{\perp}(d)$$

$$C_{\mathfrak{b}}^{\mathfrak{p}}(\varphi e) \triangleq \mathbf{if} \ \varphi \ \mathbf{then} \ C_{\mathfrak{b}}^{\mathfrak{p}}(e) \ \mathbf{else} \ C_{\mathfrak{b}}^{\mathfrak{p}}(\mathbf{fail})$$

$$C_{\mathfrak{b}}^{\mathfrak{p}}(\uparrow e) \triangleq C_{\mathfrak{b}}^{\mathfrak{b}}(e)$$

$$\mathfrak{b}\Phi \longrightarrow \Phi[\overline{f \mapsto \mathfrak{b}f}]_{f \in \text{FS}(\Phi)}$$

$$\mathfrak{b}\mathbf{fail} \longrightarrow \top$$

$$\forall h_{\bar{x} \bar{\pi}}. \Phi \triangleq \mathbf{let} \ h = \lambda \bar{x} \bar{\pi}. \mathbf{fail} \wedge \bigwedge_{g_{\bar{z} \bar{\rho}} \in \bar{\pi}} \forall \bar{z} \bar{\rho}. g \bar{z} \bar{\rho} \ \mathbf{in} \ \Phi$$

$$C_{\mathfrak{b}}^{\top}(h) \triangleq h \qquad C_{\mathfrak{b}}^{\perp}(h) \triangleq \mathfrak{b}h$$

$$C_{\mathfrak{b}}^{\mathfrak{p}}(k \bar{s} \bar{o}) \triangleq C_{\mathfrak{b}}^{\mathfrak{p}}(k) \bar{s} C_{\mathfrak{b}}^{\mathfrak{p}}(o_1) \cdots C_{\mathfrak{b}}^{\mathfrak{p}}(o_n)$$

$$C_{\mathfrak{b}}^{\mathfrak{p}}(e / h \bar{x} \bar{\pi} = d) \triangleq \mathbf{let} \ h = \lambda \bar{x} \bar{\pi}. \forall h. C_{\perp}^{\top}(d) \\ \mathbf{in} \ C_{\mathfrak{b}}^{\mathfrak{p}}(e) \wedge \forall \bar{x} \bar{\pi}. C_{\mathfrak{p}}^{\perp}(d)$$

$$C_{\mathfrak{b}}^{\mathfrak{p}}(\varphi e) \triangleq \mathbf{if} \ \varphi \ \mathbf{then} \ C_{\mathfrak{b}}^{\mathfrak{p}}(e) \ \mathbf{else} \ C_{\mathfrak{b}}^{\mathfrak{p}}(\mathbf{fail})$$

$$C_{\mathfrak{b}}^{\mathfrak{p}}(\uparrow e) \triangleq C_{\mathfrak{b}}^{\mathfrak{b}}(e)$$

$$\mathfrak{b}\Phi \longrightarrow \Phi[\overline{f \mapsto \mathfrak{b}f}]_{f \in \text{FS}(\Phi)}$$

$$\mathfrak{b}\mathbf{fail} \longrightarrow \top$$

$$\forall h_{\bar{x}\bar{\pi}}. \Phi \triangleq \mathbf{let} \ h = \lambda \bar{x} \bar{\pi}. \mathbf{fail} \wedge \bigwedge_{g_{\bar{z}\bar{\rho}} \in \bar{\pi}} \forall \bar{z} \bar{\rho}. g \bar{z} \bar{\rho} \ \mathbf{in} \ \Phi$$

$$C_{\mathfrak{b}}^{\top}(h) \triangleq h \quad C_{\mathfrak{b}}^{\perp}(h) \triangleq \mathfrak{b}h$$

$$C_{\mathfrak{b}}^{\mathfrak{p}}(\lambda \bar{x} \bar{\pi}. e) \triangleq (\lambda \bar{x} \bar{\pi}. C_{\mathfrak{b}}^{\mathfrak{p}}(e)) \wedge \mathfrak{b}(\lambda \bar{x} \bar{\pi}. C_{\neg \mathfrak{b}}^{\mathfrak{p}}(e))$$

$$C_{\mathfrak{b}}^{\mathfrak{p}}(k \bar{s} \bar{o}) \triangleq C_{\mathfrak{b}}^{\mathfrak{p}}(k) \bar{s} C_{\mathfrak{b}}^{\mathfrak{p}}(o_1) \cdots C_{\mathfrak{b}}^{\mathfrak{p}}(o_n)$$

$$C_{\mathfrak{b}}^{\mathfrak{p}}(e / h \bar{x} \bar{\pi} = d) \triangleq \mathbf{let} \ h = \lambda \bar{x} \bar{\pi}. \forall h. C_{\perp}^{\top}(d) \\ \mathbf{in} \ C_{\mathfrak{b}}^{\mathfrak{p}}(e) \wedge \forall \bar{x} \bar{\pi}. C_{\mathfrak{p}}^{\perp}(d)$$

$$C_{\mathfrak{b}}^{\mathfrak{p}}(\varphi e) \triangleq \mathbf{if} \ \varphi \ \mathbf{then} \ C_{\mathfrak{b}}^{\mathfrak{p}}(e) \ \mathbf{else} \ C_{\mathfrak{b}}^{\mathfrak{p}}(\mathbf{fail})$$

$$C_{\mathfrak{b}}^{\mathfrak{p}}(\uparrow e) \triangleq C_{\mathfrak{b}}^{\mathfrak{b}}(e)$$

$$\mathfrak{b}\Phi \longrightarrow \Phi[\overline{f \mapsto \mathfrak{b}f}]_{f \in \text{FS}(\Phi)} \quad (\Phi \wedge \Psi) s \longrightarrow \Phi s \wedge \Psi s$$

$$\mathfrak{b}\mathbf{fail} \longrightarrow \top \quad (\Phi \wedge \Psi) \Upsilon \longrightarrow \Phi \Upsilon \wedge \Psi \Upsilon$$

$$\forall h_{\bar{x} \bar{\pi}}. \Phi \triangleq \mathbf{let} \ h = \lambda \bar{x} \bar{\pi}. \mathbf{fail} \wedge \bigwedge_{g_{\bar{z} \bar{\rho}} \in \bar{\pi}} \forall \bar{z} \bar{\rho}. g \bar{z} \bar{\rho} \ \mathbf{in} \ \Phi$$

$$C_{\delta}^{\top}(h) \triangleq h \quad C_{\delta}^{\perp}(h) \triangleq \text{!}h$$

$$C_{\delta}^{\text{p}}(\lambda \bar{x} \bar{\pi}. e) \triangleq (\lambda \bar{x} \bar{\pi}. C_{\delta}^{\text{p}}(e)) \wedge \text{!}(\lambda \bar{x} \bar{\pi}. C_{\delta}^{\neg \text{p}}(e))$$

$$C_{\delta}^{\text{p}}(k \bar{s} \bar{o}) \triangleq C_{\delta}^{\text{p}}(k) \bar{s} C_{\delta}^{\text{p}}(o_1) \cdots C_{\delta}^{\text{p}}(o_n)$$

$$C_{\delta}^{\text{p}}(e / h \bar{x} \bar{\pi} = d) \triangleq \text{let } h = \lambda \bar{x} \bar{\pi}. \forall h. C_{\perp}^{\top}(d) \\ \text{in } C_{\delta}^{\text{p}}(e) \wedge \forall \bar{x} \bar{\pi}. C_{\text{p}}^{\perp}(d)$$

$$C_{\delta}^{\text{p}}(\varphi e) \triangleq \text{if } \varphi \text{ then } C_{\delta}^{\text{p}}(e) \text{ else } C_{\delta}^{\text{p}}(\text{fail})$$

$$C_{\delta}^{\text{p}}(\uparrow e) \triangleq C_{\delta}^{\text{d}}(e) \quad C_{\delta}^{\text{p}}(\downarrow e) \triangleq C_{\text{p}}^{\text{p}}(e)$$

$$\text{!}\Phi \longrightarrow \Phi[\overline{f \mapsto \text{!}f}]_{f \in \text{FS}(\Phi)} \quad (\Phi \wedge \Psi) s \longrightarrow \Phi s \wedge \Psi s$$

$$\text{!}\text{fail} \longrightarrow \top \quad (\Phi \wedge \Psi) \Upsilon \longrightarrow \Phi \Upsilon \wedge \Psi \Upsilon$$

$$\forall h_{\bar{x} \bar{\pi}}. \Phi \triangleq \text{let } h = \lambda \bar{x} \bar{\pi}. \text{fail} \wedge \bigwedge_{g_{\bar{z} \bar{\rho}} \in \bar{\pi}} \forall \bar{z} \bar{\rho}. g \bar{z} \bar{\rho} \text{ in } \Phi$$

ρ, q, r

reference

 $\pi, \varrho ::= h [\bar{q}] \ \&\bar{p} \ \bar{x} \ \bar{\pi}$

prototype

 $k, o ::= h$
| $\lambda \ \&\bar{p} \ \bar{x} \ \bar{\pi} . e$

callable

 $e, d ::= k \ \&\bar{r} \ \bar{s} \ \bar{o}$
| $e / h [\bar{q}] \ \&\bar{p} \ \bar{x} \ \bar{\pi} = d$
| φe
| $\uparrow e$

expression

$h [\bar{q}]$ – pre-write annotation, \bar{q} may be modified before h is called

```

factorial (n: int) (return (m: int))
= { n ≥ 0 }
  allocate 1 (λ&r: int.
    ↑ allocate n (λ&k: int.
      fact
      / fact [r k]
      = { 0 ≤ k ≤ n ∧ r · k! = n! }
        ↑ if (k > 0) (λ. assign &r (r * k)
                      (λ. assign &k (k - 1)
                        (λ. fact)))
          (λ. break))
      / break [r] = { r = n! } ↑ return r)

```

```

allocate (v: int) (return (&r: int) { r = v })
assign (&r: int) (v: int) (return [r] { r = v })

```



```

factorial (n: int) (return (m: int))
= { n ≥ 0 }
  allocate int 1 (λ&r: int.
    ↑ allocate int n (λ&k: int.
      fact
      / fact [r k]
      = { 0 ≤ k ≤ n ∧ r · k! = n! }
        ↑ if (k > 0) (λ. assign int &r (r * k)
                      (λ. assign int &k (k - 1)
                        (λ. fact)))
          (λ. break))
      / break [r] = { r = n! } ↑ return r)

```

```

allocate α (v: α) (return (&r: α) { r = v })
assign α (&r: α) (v: α) (return [r] { r = v })

```

No-alias type system:

$$\frac{\Gamma, \Delta' \vdash e \text{ wt} \quad \Delta' \text{ is } \Delta \text{ with all handler prototypes removed}}{\Gamma, \&r, \Delta \vdash (e \ \&r) \text{ wt}}$$

- can be further refined by tracking actual reference dependencies

Effect computation – to verify and infer the pre-write annotations

No-alias type system:

$$\frac{\Gamma, \Delta' \vdash e \text{ wt} \quad \Delta' \text{ is } \Delta \text{ with all handler prototypes removed}}{\Gamma, \&r, \Delta \vdash (e \ \&r) \text{ wt}}$$

- can be further refined by tracking actual reference dependencies

Effect computation – to verify and infer the pre-write annotations

Transformation into an equivalent pure program:

$$\begin{array}{l} \text{assign } \&r \ (r * k) \\ (\lambda. \text{assign } \&k \ (k - 1)) \\ (\lambda. \text{fact}) \end{array} \quad \Rightarrow \quad \begin{array}{l} \text{assign } r \ (r * k) \\ (\lambda r'. \text{assign } k \ (k - 1)) \\ (\lambda k'. \text{fact } r' \ k') \end{array}$$

- pre-writes are converted into term parameters
- fine-grained state monad: send only the relevant part of the state

Krivine-style evaluator over COMA expressions – no intermediate HOL

A few ways to speed up the computation, e.g. $C_{\perp}^{\perp}(e) \equiv \mathfrak{h} C_{\delta}^p(e) \equiv \top$

On-the-fly factorization of selected handlers:

$$(\forall x. \varphi \rightarrow h s) \wedge (\forall y. \psi \rightarrow h t) \implies \\ \forall z. ((\exists x. \varphi \wedge z = s) \vee (\exists y. \psi \wedge z = t)) \rightarrow h z$$

- no factorized handlers \approx traditional WP
- factorize all eligible handlers \approx compact VC à la Flanagan & Saxe

Further into **control structures**: iterators, coroutines, unstructured code?

Further into **mutable state**: ownership, borrowing, prophecy variables?

Scalable **implementation**, good heuristics for subgoal factorization

Nice surface syntax, extensive **case studies**, integration into WHY3