

# Time debits in nested thunks: a proof of Okasaki's banker's queue

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- 1 Introduction
- 2 Iris<sup>\$</sup> in a nutshell
- 3 An API for thunks
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# A purely functional queue

We can implement an immutable queue using two lists *front* and *rear*:

```
type 'α queue = 'α list × 'α list
```

```
let snoc (front, rear) x =  
  (front, x :: rear)           – insert into rear list
```

```
let pop (front, rear) =  
  match front with           – if front is non-empty...  
  | x :: front' → Some (x, (front', rear)) – ...pop its head  
  | [] →                   – otherwise...  
    match List.rev rear with – ...reverse rear to front (costly)...  
    | x :: front' → Some (x, (front', [])) – ...and pop head  
    | [] → None
```

## Time cost of the purely functional queue

- *snoc*: worst time  $\mathcal{O}(1)$
- *pop*: worst time  $\mathcal{O}(n)$

Say that each function call “costs” \$1; then:

- *snoc* costs \$1 at worst
- *pop* costs  $\$(n + 1)$  at worst

Too pessimistic! The “banker’s method” (Tarjan, 1985) gives constant amortized costs:

- *snoc* costs \$2  
*we save \$1 extra for each inserted element, covering for that element’s reversal*
- *pop* costs \$1  
*reversal is pre-paid by snocs, so we only need \$1 more for the call to pop itself*

Issue: we can't spend time credits twice

```
let q = snoc (snoc (snoc nil 1) 2) 3 in
```

```
let (x1, q1) = pop q in   - we spend our savings here
```

```
let (x2, q2) = pop q in   - wrong! we don't have any savings anymore
```

...

⇒ Amortized complexity breaks if an old version of the queue is used

Idea (Okasaki, 1999):

- ① compute reversals once ⇒ memoize them
- ② share reversals among futures ⇒ suspend them ahead of time

⇒ **Laziness!** We use a **stream**, i.e., a list computed on-demand

```
type 'α stream = 'α cell thunk
```

```
and 'α cell = Nil | Cons of 'α × 'α stream
```

Tradeoff: suspending too early would create too many thunks

**type** 'α queue = int × 'α stream × int × 'α list

We enforce that  $|f| \geq |r|$ :

**let** rebalance ((lenf, f, lenr, r) as q) =

**assert** (lenf + 1 ≥ lenr) ;

**if** lenf ≥ lenr **then** q **else**    – re-establish inv. when r grows larger than f:  
    (lenf + lenr, Stream.append f (Stream.rev\_of\_list r), 0, [])  
                                  – ↑ create a thunk that will reverse r when forced

**let** snoc (lenf, f, lenr, r) x =

  rebalance (...)                   – rebalance with element inserted into r

**let** pop (lenf, f, lenr, r) =

**match** Stream.pop f **with**    – force the head thunk of f  
  ... rebalance (...) ...      – rebalance with head removed from f

Reversing  $|r|$  elements is costly, but is done after  $|f|$  elements are popped

⇒ We can **anticipate** the cost of reversal on that of the previous *pops*

⇒ Because  $|f| \geq |r|$ , each *pop* absorbs a constant cost

⇒ Everything is in constant amortized time:

- *rebalance* costs \$1 at worst
- *snoc* costs \$2 at worst
- *pop* costs (e.g.) \$5 amortized

# Why it works: credit vs. debit

The banker's queue can be used **persistently**

Key idea:

- the non-lazy queue saves **credit** for an unknown future computation  
⇒ not duplicable (cannot forge money)
- the banker's queue repays a **debit** for a known past computation  
⇒ duplicable (can waste money)

Soundness: you get nothing until you are done repaying (debit  $\neq$  loan)

Basic building blocks: **thunks**, holding debits:

$$isThink\ t\ m\ \varphi$$

Ownership is duplicable:

$$isThink\ t\ m\ \varphi \multimap isThink\ t\ m\ \varphi \star isThink\ t\ m\ \varphi$$

We can anticipate a debit:

$$\text{e.g. } \frac{isThink\ t_1\ m_1\ (\lambda t_2. isThink\ t_2\ m_2\ \varphi)}{isThink\ t_1\ (m_1 + m)\ (\lambda t_2. isThink\ t_2\ (m_2 - m)\ \varphi)}$$



**Danielsson (2008)** gives a dependent type system (in Agda) for specifying and verifying amortized costs of programs with thunks

- ad-hoc type system, not a general-purpose program logic
- explicit credit-consuming operations must be inserted in code

**Mével et al. (2019)** extend Iris with time credits  $\Rightarrow$  Iris<sup>\$</sup>

Our contribution: thunks, streams and the banker's queue (WIP) in Iris<sup>\$</sup>

This talk: thunks

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Iris extended with an assertion  $\$n$  ( $n \in \mathbb{N}$ ) satisfying a few laws:

$$\begin{aligned} & \vdash \$0 \\ \$ (m + n) & \equiv \$m \star \$n \end{aligned}$$

We can throw credits away, but not forge nor duplicate them

Each execution step **consumes**  $\$1$ :

$$\{\$1 \star \ell \mapsto v\} !\ell \{\lambda v'. v' = v\}$$

Realized as ghost state:  $\$n \triangleq [\circ n]^{\gamma_{TC}}$  in the monoid  $\text{AUTH}(\mathbb{N}, +)$

$\implies [\bullet N]^{\gamma_{TC}}$  gives the total number of time credits in existence  
(kept in an Iris invariant)

### Theorem (Soundness)

*If  $\{ \$n \} e \{ True \}$  is derivable in Iris<sup>\$</sup>, then program  $e$  is safe and terminates in at most  $n$  steps.*

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```
type 'α thunk = 'α thunk_contents ref
```

```
and 'α thunk_contents =
```

```
| Unevaluated of (unit → 'α)
```

```
| Evaluated of 'α
```

```
let create f =
```

```
  ref (Unevaluated f)
```

```
let force t =
```

```
  match ! t with
```

```
  | Unevaluated f →
```

```
    let v = f () in      - evaluate the thunk
```

```
    t := Evaluated v ;   - memoize the result
```

```
    v
```

```
  | Evaluated v →
```

```
    v
```

Note: no re-entrancy detection (2 states only)

⇒ a static proof obligation will be needed

We want a persistent assertion  $isThink\ t\ m\ \varphi$  such that:

$$\frac{\text{OVERESTIMATE} \quad isThink\ t\ m_1\ \varphi \quad m_1 \leq m_2}{isThink\ t\ m_2\ \varphi}$$

$$\frac{\text{PAY} \quad isThink\ t\ m\ \varphi \quad \$p}{\Rightarrow isThink\ t\ (m - p)\ \varphi}$$

$$\frac{\text{ANTICIPATE+DEDUCE} \quad isThink\ t\ m\ \varphi \quad \forall v. \$n * \varphi\ v \Rightarrow \psi\ v \quad \forall v. \text{persistent}(\psi\ v)}{\Rightarrow isThink\ t\ (m + n)\ \psi}$$

$$\frac{\{(\$n * wp\ f()\ \{\varphi\}) * \forall v. \text{persistent}(\varphi\ v)\} \quad \text{create } f}{\{\lambda t. isThink\ t\ n\ \varphi\}} \quad \frac{\{isThink\ t\ 0\ \varphi\} \quad \text{force } t}{\{\lambda v. \varphi\ v\}}$$

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ANTICIPATE+DEDUCE

$$\frac{isThink\ t\ m\ \varphi \quad \forall v. \$n * \varphi\ v \Rightarrow \psi\ v \quad \forall v. \text{persistent}(\psi\ v)}{\Rightarrow isThink\ t\ (m + n)\ \psi}$$

$$\left\{ (\$n * wp\ f() \{ \varphi \}) * \forall v. \text{persistent}(\varphi\ v) \right\} \quad \left\{ isThink\ t\ 0\ \varphi \right\}$$

$$\begin{array}{l} \text{create } f \\ \left\{ \lambda t. isThink\ t\ n\ \varphi \right\} \end{array} \quad \begin{array}{l} \text{force } t \\ \left\{ \lambda v. \varphi\ v \right\} \end{array}$$



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$$\frac{\text{ANTICIPATE+DEDUCE} \quad isThink\ t\ m\ \varphi \quad \forall v. \$n * \Box \varphi\ v \Rightarrow \Box \psi\ v}{\Rightarrow isThink\ t\ (m + n)\ \psi}$$

$$\begin{array}{cc} \{ \$n * wp\ f() \{ \Box \varphi \} \} & \{ isThink\ t\ 0\ \varphi \} \\ \text{create } f & \text{force } t \\ \{ \lambda t. isThink\ t\ n\ \varphi \} & \{ \lambda v. \Box \varphi\ v \} \end{array}$$

We want a persistent assertion  $isThink\ t\ m\ \varphi$  such that:

A think is evaluated only once:  
these arrows need not be persistent

$$\frac{\text{OVERESTIMATE} \quad isThink\ t\ m_1\ \varphi \quad m_1 \leq m_2}{isThink\ t\ m_2\ \varphi} \quad \frac{isThink\ t\ m\ \varphi \quad \$p}{\Rightarrow isThink\ t\ (m - p)\ \varphi}$$

$$\frac{\text{ANTICIPATE+DEDUCE} \quad isThink\ t\ m\ \varphi \quad \forall v. \$n * \Box \varphi\ v \Rightarrow \Box \psi\ v}{\Rightarrow isThink\ t\ (m + n)\ \psi}$$

$$\begin{array}{ll} \{ \$n * wp\ f() \{ \Box \varphi \} \} & \{ isThink\ t\ 0\ \varphi \} \\ \text{create } f & \text{force } t \\ \{ \lambda t. isThink\ t\ n\ \varphi \} & \{ \lambda v. \Box \varphi\ v \} \end{array}$$

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$$\frac{\text{ANTICIPATE+DED} \quad isThink\ t\ m\ \varphi \quad \boxed{\text{Re-entrenchy?}} \quad \forall v. \$n * \square \varphi\ v \Rightarrow \square \psi\ v}{\Rightarrow isThink\ t\ (m + n)\ \psi}$$

$$\begin{array}{ll} \{ \$n * wp\ f() \{ \square \varphi \} \} & \{ isThink\ t\ 0\ \varphi \} \\ \text{create } f & \text{force } t \\ \{ \lambda t. isThink\ t\ n\ \varphi \} & \{ \lambda v. \square \varphi\ v \} \end{array}$$

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$$\frac{\text{ANTICIPATE+DEDUCE} \quad isThink\ t\ m\ \varphi \quad \forall v. \$n \star \Box \varphi\ v \Rightarrow \Box \psi\ v}{\Rightarrow isThink\ t\ (m + n)\ \psi} \quad \frac{\text{CANFORCEEXCL} \quad canForce \quad canForce}{False}$$

$$\left\{ \$n \rightarrow wp\ f()\ \{\Box \varphi\}\ \right\} \quad \left\{ isThink\ t\ 0\ \varphi \star canForce \right\}$$

$$\quad \text{create } f \quad \quad \text{force } t$$

$$\left\{ \lambda t. isThink\ t\ n\ \varphi \right\} \quad \left\{ \lambda v. \Box \varphi\ v \star canForce \right\}$$

where  $canForce$  is owned at the beginning of the world

We want a persistent assertion  $isThink\ t\ m\ \varphi$  such that:

$$\frac{\text{OVERESTIMATE} \quad isThink\ t\ m_1\ \varphi \quad m_1 \leq m_2}{isThink\ t\ m_2\ \varphi}$$

$$\frac{\text{PAY} \quad isThink\ t\ m\ \varphi \quad \$p}{\Rightarrow isThink\ t\ (m - p)\ \varphi}$$

$$\frac{\text{ANTICIPATE+} \quad isThink\ t\ m\ \varphi \quad \forall v. \$n * \Box \varphi v \Rightarrow \Box \psi v \quad \text{canForce} \quad \text{canForce}}{\Rightarrow isThink\ t\ (m + n)\ \psi} \quad \text{CL} \quad \text{False}$$

$$\left\{ \$n * wp\ f() \{ \Box \varphi \} \right\} \quad \left\{ isThink\ t\ 0\ \varphi * canForce \right\}$$

$$\quad \text{create } f \quad \quad \text{force } t$$

$$\left\{ \lambda t. isThink\ t\ n\ \varphi \right\} \quad \left\{ \lambda v. \Box \varphi v * canForce \right\}$$

where  $canForce$  is owned at the beginning of the world

We want a persistent assertion  $isThink\ t\ \mathcal{N}\ m\ \varphi$  such that:

$$\frac{\text{OVERESTIMATE} \quad isThink\ t\ \mathcal{N}\ m_1\ \varphi \quad m_1 \leq m_2}{isThink\ t\ \mathcal{N}\ m_2\ \varphi}$$

$$\frac{\text{PAY} \quad isThink\ t\ \mathcal{N}\ m\ \varphi \quad \$p}{\Rightarrow isThink\ t\ \mathcal{N}\ (m - p)\ \varphi}$$

$$\frac{\text{ANTICIPATE+DEDUCE} \quad isThink\ t\ \mathcal{N}\ m\ \varphi \quad \forall v. \$n * \Box \varphi v \Rightarrow \Box \psi v}{\Rightarrow isThink\ t\ \mathcal{N}\ (m + n)\ \psi} \quad \frac{\text{CANFORCEEXCL} \quad canForce\ \mathcal{N}_1 \quad canForce\ \mathcal{N}_2}{(\uparrow \mathcal{N}_1) \cap (\uparrow \mathcal{N}_2) = \emptyset}$$

$$\begin{array}{cc} \{ \$n * wp\ f() \{ \Box \varphi \} \} & \{ isThink\ t\ \mathcal{N}\ 0\ \varphi * canForce\ \mathcal{N} \} \\ \text{create } f & \text{force } t \\ \{ \lambda t. isThink\ t\ \mathcal{N}\ n\ \varphi \} & \{ \lambda v. \Box \varphi v * canForce\ \mathcal{N} \} \end{array}$$

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$$\frac{\text{PAY} \quad isThink\ t\ \mathcal{N}\ m\ \varphi \quad \$p}{\Rightarrow isThink\ t\ \mathcal{N}\ (m - p)\ \varphi}$$

ANTICIPATE+D ...But how to pass the token to the inner think?

$$\frac{isThink\ t\ \mathcal{N}\ m\ \varphi \quad \forall v. \$n * \Box \varphi v \Rightarrow \Box \varphi v \quad canForce\ \mathcal{N}_1 \quad canForce\ \mathcal{N}_2}{\Rightarrow isThink\ t\ \mathcal{N}\ (m + n)\ \psi \quad (\uparrow \mathcal{N}_1) \cap (\uparrow \mathcal{N}_2) = \emptyset}$$

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where  $canForce\ \top$  is owned at the beginning of the world

We want a persistent assertion  $isThink\ t\ \mathcal{N}\ m\ R\ \varphi$  such that:

OVERESTIMATE

$$\frac{isThink\ t\ \mathcal{N}\ m_1\ R\ \varphi \quad m_1 \leq m_2}{isThink\ t\ \mathcal{N}\ m_2\ R\ \varphi}$$

PAY

$$\frac{isThink\ t\ \mathcal{N}\ m\ R\ \varphi \quad \$p}{\Rightarrow isThink\ t\ \mathcal{N}\ (m - p)\ R\ \varphi}$$

ANTICIPATE+DEDUCE

$$\frac{isThink\ t\ \mathcal{N}\ m\ R\ \varphi \quad \forall v. \$n \star \Box \varphi v \Rightarrow \Box \psi v}{\Rightarrow isThink\ t\ \mathcal{N}\ (m + n)\ R\ \psi}$$

CANFORCEEXCL

$$\frac{canForce\ \mathcal{N}_1 \quad canForce\ \mathcal{N}_2}{(\uparrow \mathcal{N}_1) \cap (\uparrow \mathcal{N}_2) = \emptyset}$$

$$\{\$n \star R \star wp\ f()\ \{\Box \varphi \star R\}\}$$

*create f*

$$\{\lambda t. isThink\ t\ \mathcal{N}\ n\ R\ \varphi\}$$

$$\{isThink\ t\ \mathcal{N}\ 0\ R\ \varphi \star canForce\ \mathcal{N} \star R\}$$

*force t*

$$\{\lambda v. \Box \varphi v \star canForce\ \mathcal{N} \star R\}$$

where  $canForce\ \top$  is owned at the beginning of the world



ANTICIPATE+DEDUCE

$$\frac{isThink\ t\ m\ \varphi \quad \forall v. \$n * \Box \varphi\ v \Rightarrow \Box \psi\ v}{\Rightarrow isThink\ t\ (m + n)\ \psi}$$

The following is nonsensical, the think's post-cond. must be persistent:

ANTICIPATE

$$\frac{isThink\ t\ m\ \varphi}{\Rightarrow isThink\ t\ (m + n)\ (\$n * \varphi)}$$

$\Rightarrow$  We bake deduction with anticipation

$\Rightarrow n = 0$  gives a deduction rule which allows ghost updates

Rules PAY and ANTICIPATE+DEDUCE allow to derive e.g.:

$$\frac{isThink\ t_1\ m_1\ (\lambda t_2. isThink\ t_2\ m_2\ \varphi)}{\Rightarrow isThink\ t_1\ (m_1 + m)\ (\lambda t_2. isThink\ t_2\ (m_2 - m)\ \varphi)}$$

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# Tentative invariant

(assuming a ghost name  $\gamma_t$  for each location  $t$ , by convenience)

$$\mathit{thinkInv} \ t \ n \ \varphi \triangleq \exists p. \boxed{\bullet p}^{\gamma_t} \star \bigvee \begin{cases} \exists f. t \mapsto U f \star \$p \star (\$n \multimap wp f() \{\square \varphi\}) \\ \exists v. t \mapsto E v \star \square \varphi v \end{cases}$$

$$\mathit{isThink} \ t \ m \ \varphi \triangleq \exists n. \boxed{\circ (n - m)}^{\gamma_t} \star \boxed{\mathit{thinkInv} \ t \ n \ \varphi} \quad (\text{slightly wrong, see next slide})$$

Ghost state in  $\text{AUTH}(\mathbb{N}, \max)$  records the number of accumulated credits:

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  - $n$  credits are **needed** in total
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OVERESTIMATE:  $\boxed{\circ(n-m_1)}^{\gamma} \multimap \boxed{\circ(n-m_2)}^{\gamma}$  if  $m_1 \leq m_2$

PAY:  $\boxed{\bullet p}^{\gamma} \Rightarrow \boxed{\bullet(p+p')}^{\gamma} \star \boxed{\circ(p+p')}^{\gamma}$

## Re-entrancy and non-atomic invariants

Problem: an Iris **invariant** can only stay opened around one atomic step

$$isThink\ t \quad m\ \varphi \triangleq \exists n. \boxed{\circ(n - m)}^{\gamma_t} \star \boxed{thinkInv\ t\ n\ \varphi}$$

## Re-entrancy and non-atomic invariants

Problem: an Iris invariant can only stay opened around one atomic step

$$isThink\ t \quad m\ \varphi \triangleq \exists n. \boxed{\circ(n - m)}^{\gamma_t} \star \boxed{thinkInv\ t\ n\ \varphi}$$

Solution: use a “**non-atomic invariant**” (Iris’ convenience library)



# Re-entrancy and non-atomic invariants

Problem: an Iris invariant can only stay opened around one atomic step

$$\begin{aligned} isThink\ t \quad m\ \varphi &\triangleq \exists n. \boxed{\circ(n - m)}^{?t} \star \boxed{thinkInv\ t\ n\ \varphi} \\ canForce &\triangleq naInvTok \end{aligned}$$

Solution: use a “**non-atomic invariant**” (Iris’ convenience library)

A NA invariant is guarded by an **exclusive token**

# Re-entrancy and non-atomic invariants

Problem: an Iris invariant can only stay opened around one atomic step

$\mathcal{N}$  : namespace

$$\begin{aligned} \text{isThink } t \ \mathcal{N} \ m \ \varphi &\triangleq \exists n. \boxed{\circ(n - m)}^{\gamma_t} \star \boxed{\text{thinkInv } t \ n \ \varphi}^{\mathcal{N}} \\ \text{canForce } \mathcal{N} &\triangleq \text{nalInvTok } (\uparrow \mathcal{N}) \end{aligned}$$

Solution: use a “**non-atomic invariant**” (Iris’ convenience library)

A NA invariant is guarded by an **exclusive token**

$$\begin{aligned} &\vdash \text{nalInvTok } \emptyset \\ \text{nalInvTok } (\mathcal{E}_1 \uplus \mathcal{E}_2) &\equiv \text{nalInvTok } \mathcal{E}_1 \star \text{nalInvTok } \mathcal{E}_2 \end{aligned}$$

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Solution: use a “**non-atomic invariant**” (Iris’ convenience library)

A NA invariant is guarded by an **exclusive token**

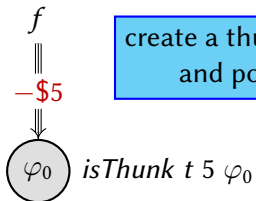
$$\begin{aligned} &\vdash \text{nalInvTok } \emptyset \\ \text{nalInvTok } (\mathcal{E}_1 \uplus \mathcal{E}_2) &\equiv \text{nalInvTok } \mathcal{E}_1 \star \text{nalInvTok } \mathcal{E}_2 \end{aligned}$$

Thus, it can stay opened for as long as we want:

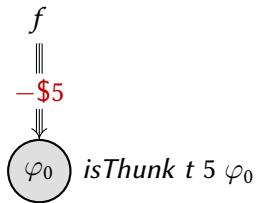
$$\frac{\text{NA-INV-ACC} \quad \boxed{P}^{\mathcal{N}} \quad \text{nalInvTok } (\uparrow \mathcal{N}) \quad \uparrow \mathcal{N} \subseteq \mathcal{E}}{\mathcal{E} \Vdash^{\mathcal{E}} \triangleright P \star (\triangleright P \ \mathcal{E} \Rrightarrow^{\mathcal{E}} \text{nalInvTok } (\uparrow \mathcal{N}))}$$

- persistence ✓
- OVERESTIMATE ✓
- PAY ✓
- ANTICIPATE+DEDUCE ✗
- CANFORCEEXCL ✓
- spec of *create* ✓
- spec of *force* ✓

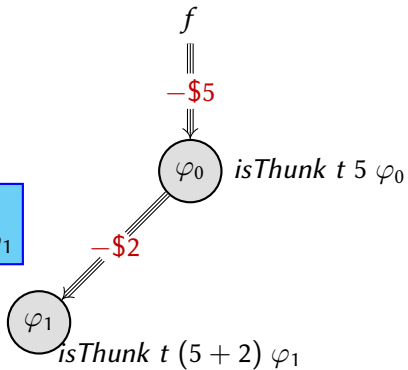
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- 6 Streams



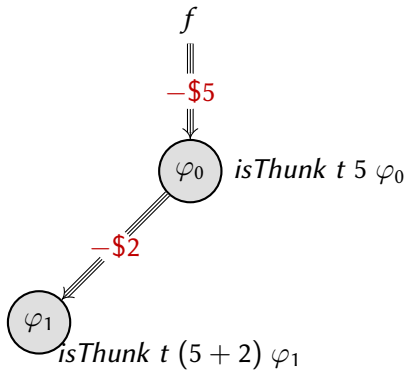
create a think with debit 5  
and post-cond.  $\varphi_0$

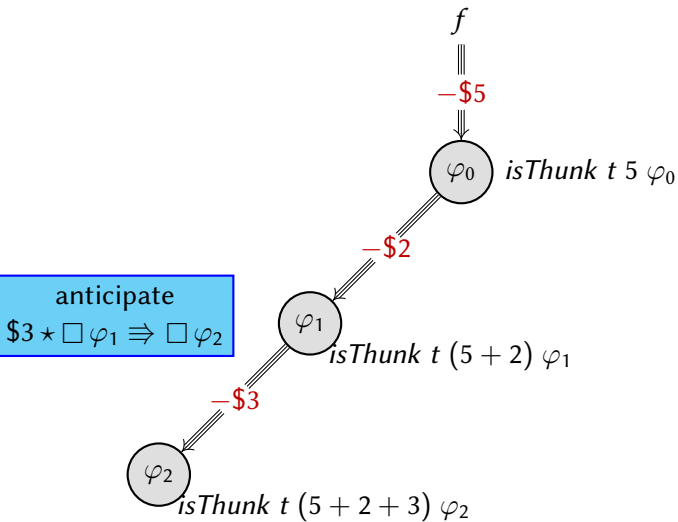


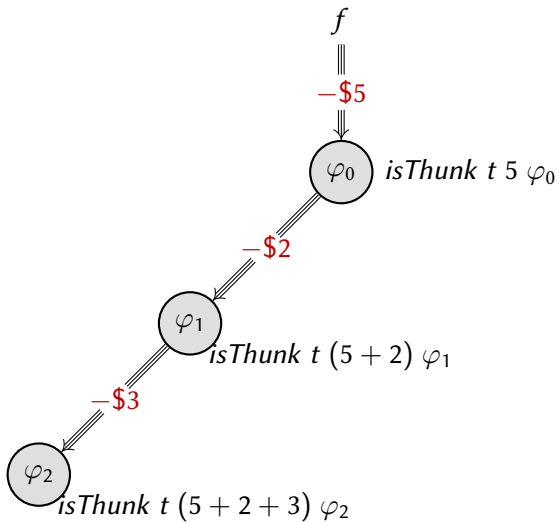
anticipate  
 $\$2 * \Box \varphi_0 \Rightarrow \Box \varphi_1$

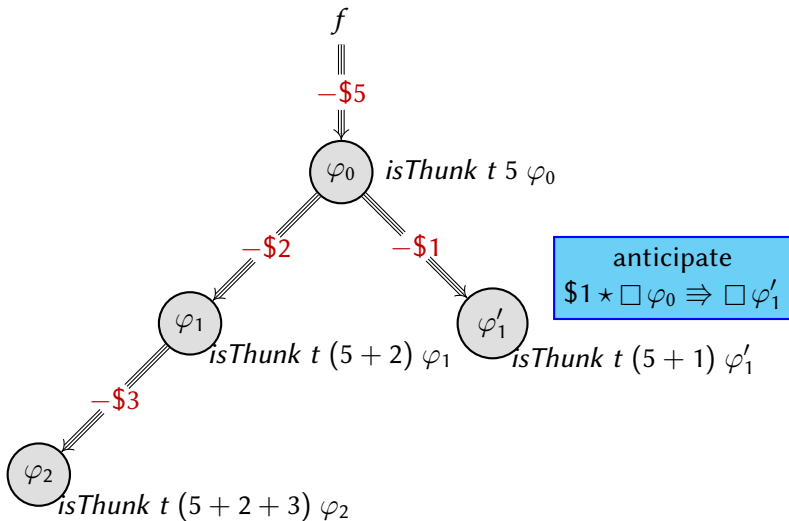


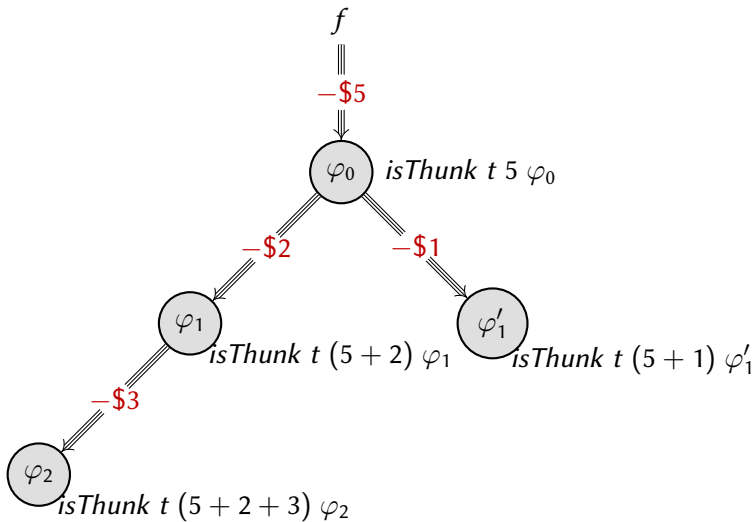


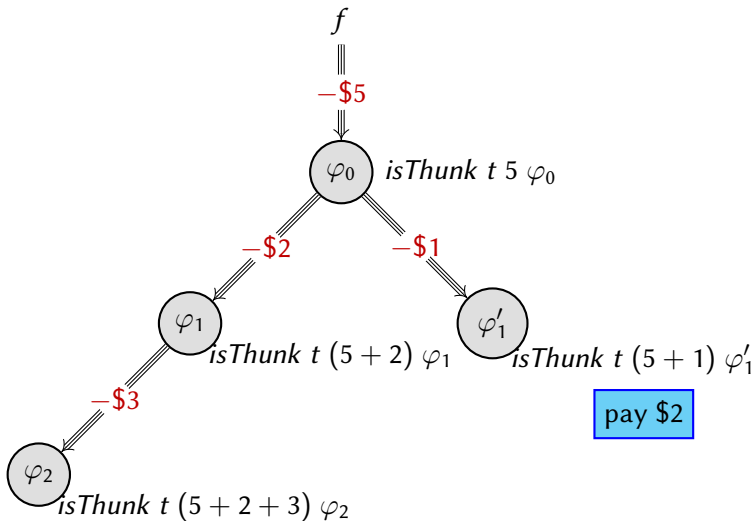


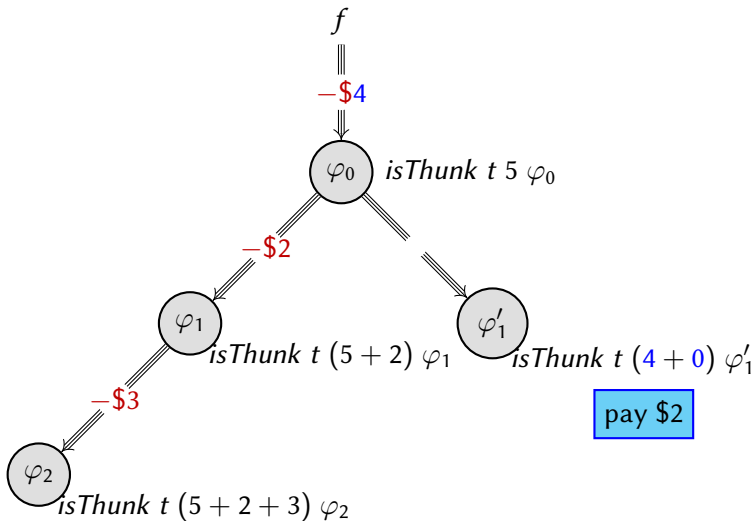


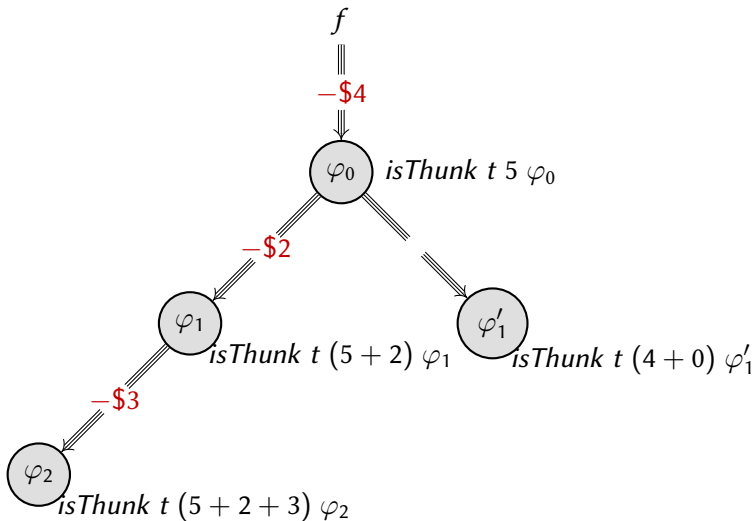




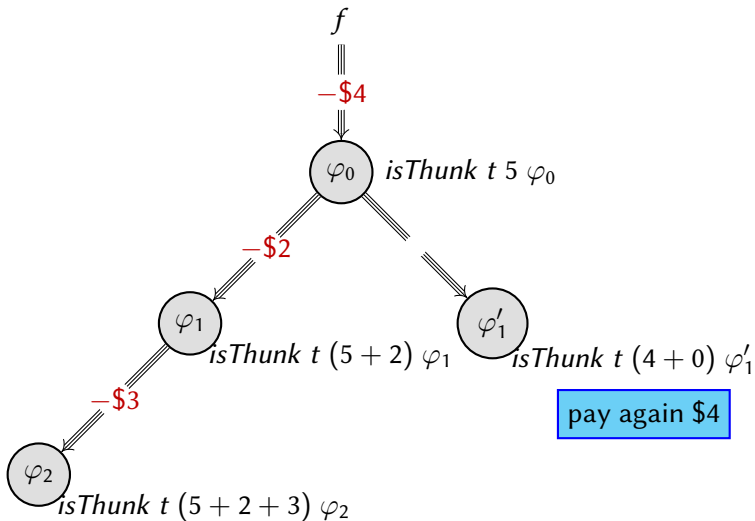


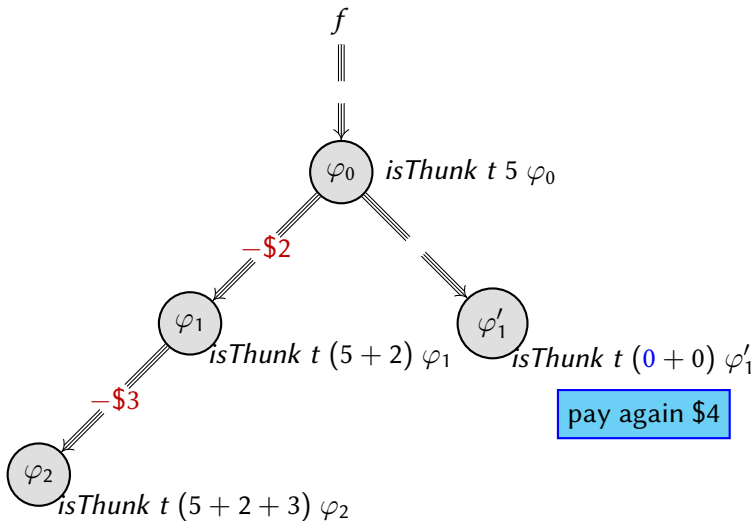


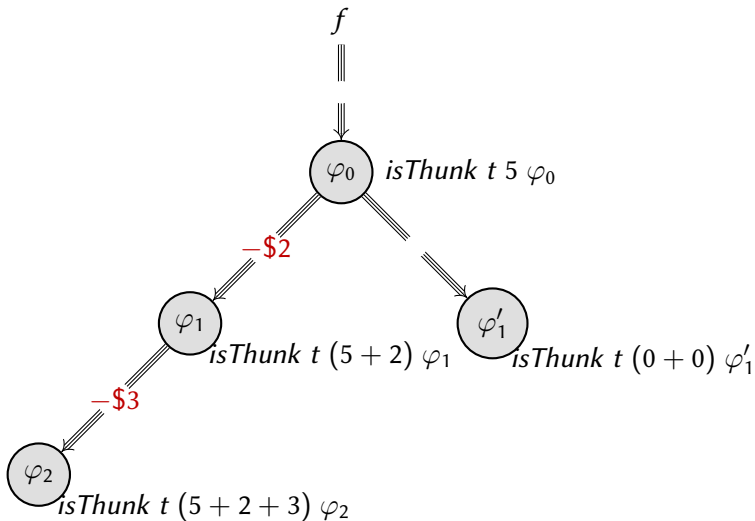


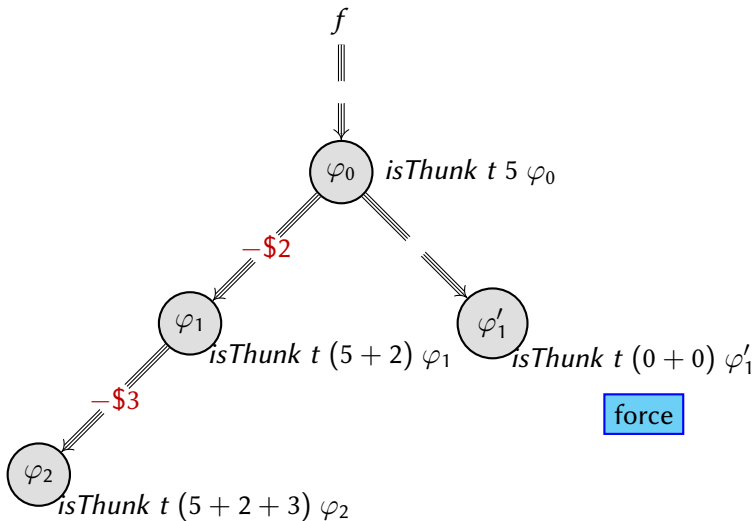


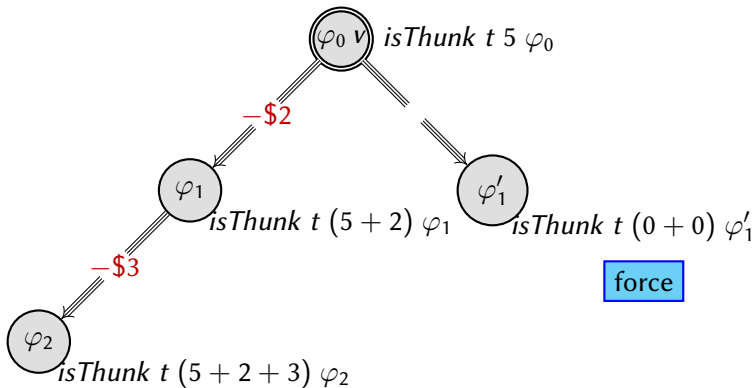


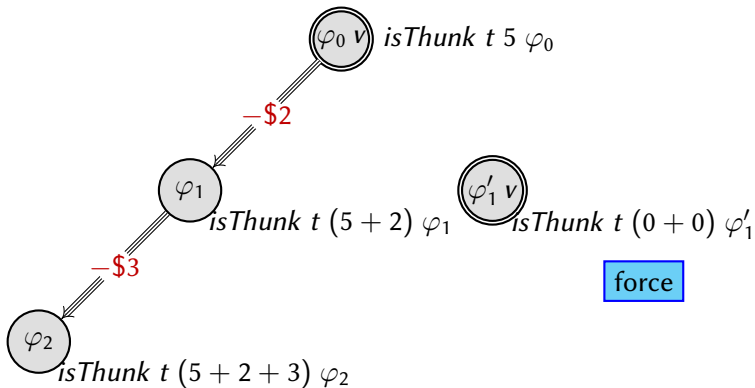


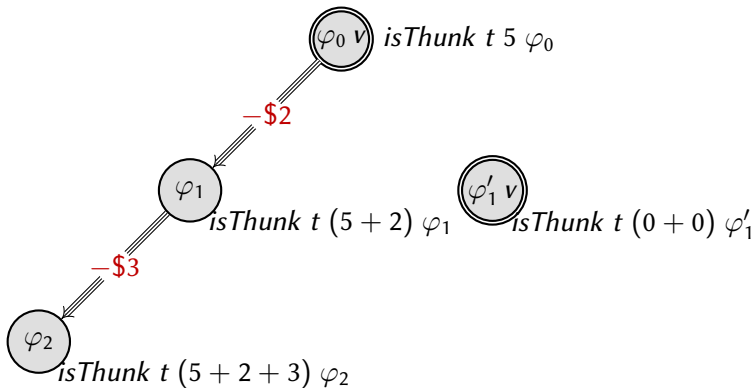


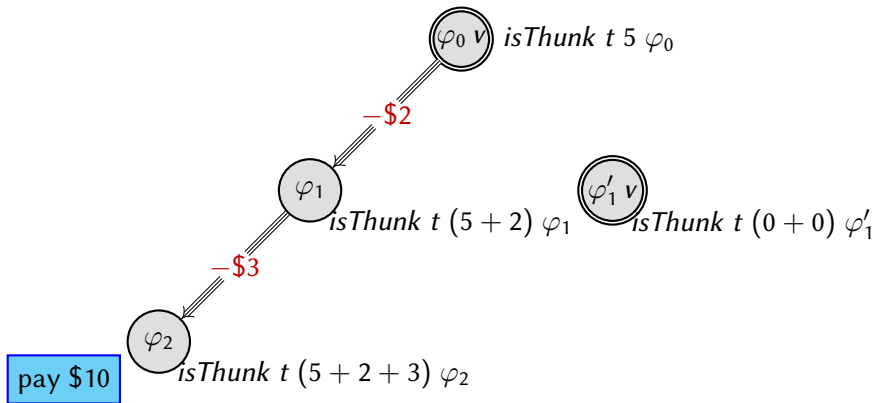






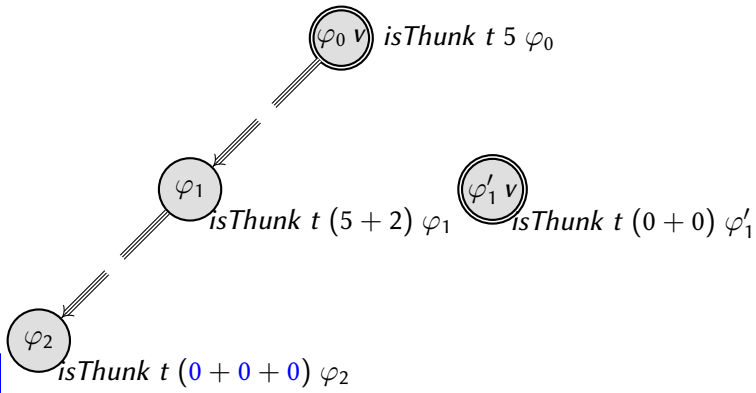




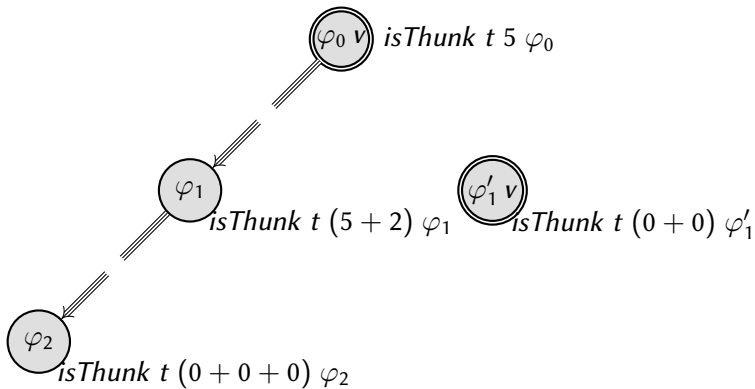


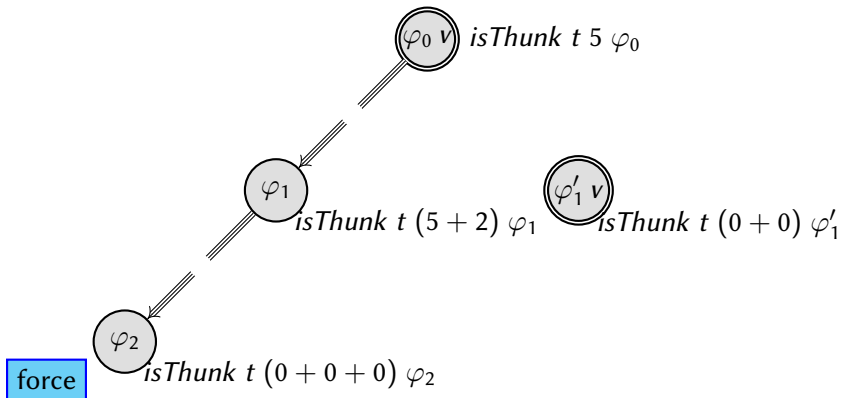


(\$5 are wasted)



pay \$10





$\varphi_0 \vee$  *isThink*  $t$  5  $\varphi_0$

$\varphi_1 \vee$

*isThink*  $t$  (5 + 2)  $\varphi_1$

$\varphi'_1 \vee$

*isThink*  $t$  (0 + 0)  $\varphi'_1$

$\varphi_2$

*isThink*  $t$  (0 + 0 + 0)  $\varphi_2$

force

$\varphi_0 \vee$  *isThink*  $t$  5  $\varphi_0$

$\varphi_1 \vee$  *isThink*  $t$  (5 + 2)  $\varphi_1$       $\varphi'_1 \vee$  *isThink*  $t$  (0 + 0)  $\varphi'_1$

**force**  $\varphi_2 \vee$  *isThink*  $t$  (0 + 0 + 0)  $\varphi_2$

Idea: stack a new invariant each time ANTICIPATE+DEDUCE is used

⇒ Tower of invariants

(assuming a ghost name  $\gamma_{t,d}$  for each location  $t$ , and integer  $d$ , by convenience)

$$\mathit{thinkInv} \ t \ n \ \varphi \triangleq \exists p. \boxed{\bullet p}^{\gamma_{t,0}} \star \bigvee \left\{ \begin{array}{l} \exists f. t \mapsto U f \star \$p \star (\$n \rightarrow \mathit{wp} f()) \{ \square \varphi \} \\ \exists v. t \mapsto E v \star \square \varphi v \end{array} \right.$$

$$\mathit{csqInv} \ t \ d \ n \ \varphi \ \psi \triangleq \exists p. \boxed{\bullet p}^{\gamma_{t,d}} \star \bigvee \left\{ \begin{array}{l} \$p \star (\forall v. \$n \star \square \varphi v \Rightarrow \square \psi v) \\ \square \psi v \end{array} \right.$$

$$\mathit{isThink} \ t \ 0 \ m \ \varphi \triangleq \exists p, n. 0 \leq m-p \leq n \star \boxed{\circ p}^{\gamma_{t,0}} \star \boxed{\mathit{thinkInv} \ t \ n \ \varphi}$$

$$\begin{aligned} \mathit{isThink} \ t \ d \ m \ \varphi \triangleq & \exists p, n, \psi. 0 \leq m-p \leq n \star \boxed{\circ p}^{\gamma_{t,d}} \star \boxed{\mathit{csqInv} \ t \ n \ \psi \ \varphi} \\ & \star \mathit{isThink} \ t \ (d-1) \ (m-n+p) \ \psi \end{aligned}$$

Each level ( $d \in \mathbb{N}$ ) has its own vault ( $\gamma_{t,d}$ ) for filling a debit

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# Implementation of streams

**type** 'α stream = 'α cell *thunk*  
**and** 'α cell = Nil | Cons **of** 'α × 'α stream

– a stream is computed on-demand

**let** pop (xs : 'α stream) =  
  **match** *Thunk.force* xs **with**  
  | Cons (x, xs') → Some (x, xs')  
  | Nil → None

**let** rev\_of\_list (xs : 'α list) : 'α stream =

**let rec** rev\_app (xs : 'α list) (ys : 'α cell) =  
    **match** xs **with**  
    | x :: xs' → rev\_app xs' (Cons (x, *Thunk.create@@fun()* → ys))  
    | [] → ys **in**  
  *Thunk.create@@fun()* → *rev\_app* xs Nil

– *rev\_app* reverses the list eagerly

– ↓ these new thunks have cost 0

– this leading thunk is costly

**let rec** append (xs : 'α stream) (ys : 'α stream) =

*Thunk.create@@fun()* →  
  **match** *Thunk.force* xs **with**  
  | Cons (x, xs') → Cons (x, append xs' ys)  
  | Nil → *Thunk.force* ys

– this thunk has a constant overhead



A stream is a thunk which computes a value and another thunk (its tail)

A stream has a list of debits, those required for computing the successive elements of the stream:

$$\begin{aligned}
 \text{isStream } s \ [m_0, \dots, m_n] \ [v_1, \dots, v_n] &\triangleq \\
 \text{isThunk } s \ m_0 \ (\lambda c_1. \exists s_1. c_1 = \text{Cons}(v_1, s_1) \star & \\
 \text{isThunk } s_1 \ m_1 \ (\lambda c_2. \exists s_2. c_2 = \text{Cons}(v_2, s_2) \star & \\
 \dots & \\
 \text{isThunk } s_n \ m_n \ (\lambda c_{n+1}. c_{n+1} = \text{Nil} \dots)) &
 \end{aligned}$$

PAYSTREAM

$$\frac{\text{isStream } s [m_0, \dots, m_n] [v_1, \dots, v_n] \quad \$p}{\text{isStream } s [m_0, \dots, m_i - p, \dots, m_n] [v_1, \dots, v_n]}$$

ANTICIPATE+OVERESTIMATESTREAM

$$\frac{\text{isStream } s [m_0, \dots, m_n] [v_1, \dots, v_n] \quad \forall k. \sum_{i \leq k} m_i \leq \sum_{i \leq k} m'_i}{\Rightarrow \text{isStream } s [m'_0, \dots, m'_n] [v_1, \dots, v_n]}$$

$$\{\text{isStream } s [m_0, \dots, m_n] [v_1, \dots, v_n] \star \text{isStream } s' [m'_0, \dots, m'_{n'}] [v'_1, \dots, v'_{n'}]\}$$

*append s s'*

$$\{\lambda t. \text{isStream } t [A + m_0, \dots, A + m_n + m'_0, m'_1, \dots, m'_{n'}] [v_1, \dots, v_n, v'_1, \dots, v'_{n'}]\}$$

$$\{\text{isList } \ell [v_1, \dots, v_n]\}$$

*rev\_of\_list*  $\ell$

$$\{\lambda s. \text{isStream } s [B \cdot n, 0, \dots, 0] [v_n, \dots, v_1]\}$$

We address nested thunks with **generations**  $g \in \mathbb{N}$ :

$isStream\ s\ [m_0, \dots, m_n]\ [v_1, \dots, v_n] \triangleq$

$\exists g_0. isThunk\ s\ \mathcal{N}(g_0)\ m_0\ (nalInvTok\ \mathcal{E}(g_0))\ (\lambda c_1. \exists s_1. c_1 = Cons(v_1, s_1)) \star$   
 $\exists g_1 \leq g_0. isThunk\ s_1\ \mathcal{N}(g_1)\ m_1\ (nalInvTok\ \mathcal{E}(g_1))\ (\lambda c_2. \exists s_2. c_2 = Cons(v_2$

...

$\exists g_n \leq g_{n-1}. isThunk\ s_n\ \mathcal{N}(g_n)\ m_n\ (nalInvTok\ \mathcal{E}(g_n))\ (\lambda c_{n+1}. c_{n+1} =$

where:

$$\mathcal{E}(g) \triangleq \top \setminus \uparrow \mathcal{N}(g)$$

$$\mathcal{E}(g) \subseteq \mathcal{E}(g+1)$$

$$\uparrow \mathcal{N}(g+1) \subseteq \uparrow \mathcal{N}(g)$$

Highlights of the proof of the banker's queue:

- anticipation of debit  
*not obvious to state*  
*even less obvious to ensure*
- generations for nested thunks

<https://gitlab.inria.fr/gmevel/iris-time-proofs>

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