

# Gradual Typing: A New Perspective

With polymorphism, unions, intersections, and much more

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G. Castagna, **V. Lanvin**, T. Petrucciani, J. Siek

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## Gradual Typing (1/3)

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Runtime checks or **casts** are then inserted **automatically** by the compiler.

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The transition is **gradual**:

$$? \preceq ? \rightarrow ? \preceq \text{Int} \rightarrow ? \preceq \text{Int} \rightarrow \text{Bool}$$

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We want to give the programmer a way to reject such cases **statically**, while still **accepting this function**.

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Unfortunately, this is **not well-typed** without additional checks, since  $\alpha$  array  $\vee$   $\alpha$  list  $\not\leq$   $\alpha$  array.



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This is **safer**, but **extremely verbose**.

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- In **Semantic subtyping**,
  - Types  $\simeq$  Sets of values
  - Subtyping  $\simeq$  Set-containment



# Pros and Cons

Set-theoretic types	Gradual types
<b>Safe</b>	Unsafe
<b>Expressive</b>	Too coarse
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Can we get the **best of both worlds?**

## Mixing the Two

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This gets even more complicated with set-theoretic types!

# Declarative Systems

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**Main idea:** interpret occurrences of `?` as arbitrary **type variables**.

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**Important remark:** this translation is **only used** to define and compute relations, and **is not done in the source program**.



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And we define **materialization** (which is the inverse of **precision**, as defined in Garcia [2013]):

$$\tau_1 \preceq \tau_2 \stackrel{\text{def}}{\iff} \exists T_1 \in \mathcal{D}(\tau_1), \sigma : \text{Vars} \rightarrow \text{GTypes}, T_1 \sigma = \tau_2$$

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As well as **gradual subtyping**:

$$\tau_1 \leq \tau_2 \stackrel{\text{def}}{\iff} \exists (T_1, T_2) \in \mathcal{D}(\tau_1) \times \mathcal{D}(\tau_2), T_1 \leq_T T_2$$

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It can be used to handle unions and intersections, by **simply plugging-in** the static version of **semantic subtyping**:

$$? \leq ? \vee \text{Int} \quad \text{Int} \wedge ? \leq ?$$

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And it is **transitive**:

$$? \preceq ? \rightarrow ? \preceq ? \rightarrow \text{Int} \preceq \text{Int} \rightarrow \text{Int}$$

Therefore it can be embedded into a type system as a **subsumption rule**.

# Declarative Type Systems

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And as a bonus, we get the **static gradual guarantee** for free!

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Hence  $\Gamma \vdash \text{data} : \alpha \text{ array}$

$\implies$  `Array.map f data` is **well-typed**.

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Subtyping cannot be used either as it is **contravariant in the domain**:

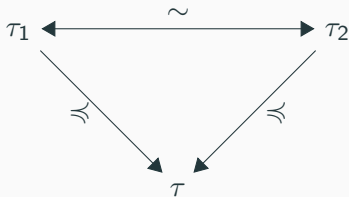
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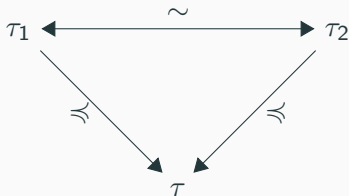
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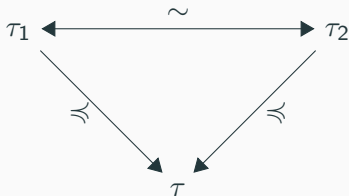


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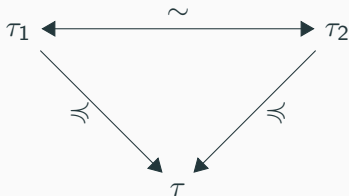


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- 3- Same results for the polymorphic system of Garcia & Cimini [2015].

## Towards a Cast Language

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**Blame** tells us where an error occurred, and **in which way** the boundary was crossed.

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Moreover, the direction of the cast **can be enforced** in the typing rules:

$$\frac{\Gamma \vdash e : \tau_1 \quad \begin{cases} p = l & \implies \tau_1 \preceq \tau_2 \\ p = \bar{l} & \implies \tau_2 \preceq \tau_1 \end{cases}}{\Gamma \vdash e \langle \tau_1 \xrightarrow{P} \tau_2 \rangle : \tau_2}$$



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**Blame safety** is an important result of the cast language that states that **only the dynamically-typed part** of the code can cause errors.

We only insert casts when crossing from **dynamic** to **static** code, and **precisely control** the direction of each cast throughout the execution. **This makes proving blame safety straightforward.**

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- We presented a simple, straightforward way of **declaratively adding gradual typing** to existing type systems and compilation systems.
- We highlight a **direct correspondence** between compilation and type derivations.
- The declarative systems enjoy **many** (almost) **free theorems** (blame safety, type preservation, static gradual guarantee).

# Algorithmic Systems

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## Part 1: Hindley-Milner

static types  $\mathcal{T}_t \ni t ::= \alpha \mid b \mid t \times t \mid t \rightarrow t$

gradual types  $\mathcal{T}_\tau \ni \tau ::= ? \mid \alpha \mid b \mid \tau \times \tau \mid \tau \rightarrow \tau$

source language  $e ::= x \mid c \mid \lambda x. e \mid \lambda x: \tau. e \mid e e \mid (e, e) \mid \pi_i e$   
 $\mid \text{let } \vec{\alpha} x = e \text{ in } e$

cast language  $E ::= \lambda^{\tau \rightarrow \tau} x. E \mid \text{let } x = E \text{ in } E \mid \Lambda \vec{\alpha}. E \mid E [\vec{t}]$   
 $\mid E \langle \tau \xrightarrow{R} \tau \rangle \mid \dots$

## Inference: Main Ideas

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- We generate **structured constraints**, rewrite them to obtain a set of **unification and materialization constraints**, and solve them by **unification**.

Note: we **never infer gradual types**, they can only be introduced by **explicit annotations**.

# Inference: Structured Constraints

We first **generate constraints** of the form<sup>1</sup>:

$$C ::= (t \dot{\leq} t) \mid (\tau \dot{\preceq} \alpha) \mid (x \dot{\preceq} \alpha) \mid \text{def } x: \tau \text{ in } C \mid \exists \vec{\alpha}. C \mid C \wedge C$$

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Note that  $\langle\langle (\lambda x: ?. x): \text{Int} \rightarrow \text{Int} \rangle\rangle$  **can be solved**, whereas  $\langle\langle (\lambda x. x): ? \rightarrow ? \rangle\rangle$  **cannot**.

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and solving it will return the unifier

$$\theta : X_1 \mapsto \text{Bool}; X_2 \mapsto \beta; X_3 \mapsto \gamma; \alpha \mapsto (\beta \rightarrow \gamma)$$

## Compilation and Results

To summarize, given an expression  $e$ , and a constraint derivation  $\mathcal{D}$  of  $\Gamma; \Delta \vdash \langle\langle e : t \rangle\rangle \rightsquigarrow D$ , we can **compute a unifier**  $\theta$  satisfying  $\mathcal{D}$ .



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Inference (and compilation) for this system is **sound**, **type-preserving** and **complete** w.r.t. the declarative system.

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For example,

```
fun x -> if (fst x) then (1 + snd x) else x
```

should be of type  $(\text{Bool} \times \text{Int}) \rightarrow (\text{Int} \mid (\text{Bool} \times \text{Int}))$

## Part 3: Adding Set-Theoretic Types

The types become:

static types  $t ::= \alpha \mid \mathbf{b} \mid t \times t \mid t \rightarrow t \mid t \vee t \mid \neg t \mid \mathbb{0}$

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**Soundness still holds** for the inference algorithm, but **completeness no longer holds**.

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Recall that subtyping is defined as an **existential quantification**.

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**This is enough to decide subtyping**

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The semantics of the cast calculus for **HM without subtyping** are basically the same as those presented by Siek et al. [2015].

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$$\begin{array}{ll} \text{[ExpandL]} & V\langle\tau \xrightarrow{R} ?\rangle \hookrightarrow V\langle\tau \xrightarrow{R} \text{gnd}(\tau)\rangle\langle\text{gnd}(\tau) \xrightarrow{R} ?\rangle \\ \text{[Collapse]} & V\langle\rho \xrightarrow{R} ?\rangle\langle ? \xrightarrow{q} \rho'\rangle \hookrightarrow V \quad \text{if } \rho = \rho' \\ \text{[Blame]} & V\langle\rho \xrightarrow{R} ?\rangle\langle ? \xrightarrow{q} \rho'\rangle \hookrightarrow \text{blame } q \quad \text{if } \rho \neq \rho' \end{array}$$

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$$\text{gnd}(\tau_1 \rightarrow \tau_2) = ? \rightarrow ? \quad \text{gnd}(\tau_1 \times \tau_2) = ? \times ? \quad \text{gnd}(b) = b$$

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We defined a **grounding operator**  $\tau_1/\tau_2$  to compute the intermediate type of a cast.

$$(\text{Int} \rightarrow \text{Int}) \vee (\text{Bool} \rightarrow \text{Bool}) / (\text{Int} \rightarrow \text{Int}) \vee ? = (\text{Int} \rightarrow \text{Int}) \vee (? \rightarrow ?)$$

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## Some Remarks About Semantics (2/2)

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The full semantics are **conservative**, but complicated and contain **six additional rules to handle corner cases**.

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- We also gave a **sound** inference algorithm for an extension of this language with set-theoretic types, which **reuses the tallying algorithm**.
- We provided **sound semantics** for a cast calculus with set-theoretic gradual types and polymorphism.

Thanks for listening!

Comments, questions, suggestions?