# Frozen inference constraints for type-directed disambiguation

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# Type-directed disambiguation

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*Type classes* (qualified types): nice inference through *constraint abstraction* excellent approach for operator overloading. Type-directed disambiguation outside qualified types

A feature where type classes are not enough: *data constructor* disambiguation.

f (K t) match t with K x  $\rightarrow u$  Type-directed disambiguation outside qualified types

A feature where type classes are not enough: *data constructor* disambiguation.

```
f (K t)
match t with K x -> u
```

- We do not want to *abstract* over *K*.
- The type of K may not be expressible as a class argument (existentials, etc.; data constructors are not functions.)
- Solution Different constructors K may have vastly different typing rules.

#### Constructor disambiguation and type inference

```
f (K t)
match t with K x -> u
```

Need program types to disambiguate K. Need the type of K to infer program types.

HM type inference:

propagation by unification (within generalization boundaries).

Bidirectional type inference (commonly used for disambiguation): leafward propagation from annotations (robust) + some lateral propagation (fragile): t u

This Work In Progress explores unification-based type disambiguation *frozen constraints*.

Constraint-based type inference: a primer

implicitly-typed 
$$t \stackrel{\text{generate}}{\Longrightarrow}$$
 constraint  $C \stackrel{\text{solve}}{\Longrightarrow}$  explicitly-typed  $t'$ 

Constraint for application t u with return type variable  $\alpha$ :

$$\llbracket t \ u \rrbracket_{\alpha} \stackrel{\mathsf{def}}{=} \exists \beta_t . \exists \gamma_u. \ ((\beta_t = \gamma_u \to \alpha) \land \llbracket t \rrbracket_{\beta_t} \land \llbracket u \rrbracket_{\gamma_u})$$

#### Frozen constraints

 $\langle \alpha \rangle f$ 

 $\alpha:$  type inference variable

f: function from partial types to constraints

waits on a type unification variable  $\alpha$ : when  $\alpha$  becomes (partly) defined as  $\tau$ , the constraint  $f(\tau)$  must be solved.

Constructor constraint (non-GADT case):

 $\llbracket K \ t \rrbracket_{\alpha} \stackrel{\text{def}}{=} \exists \beta_t. \ (\llbracket t \rrbracket_{\beta_t} \ \land \ \langle \alpha \rangle (\lambda \tau. \ \beta_t = \arg\_\mathsf{type}(\tau, K)))$ 

Principled (and principal) inference with type-disambiguation. (Maybe too restrictive?)

Difficult to combine with generalization!

Practical difficulty: generalization (1/2)

If  $\langle \alpha \rangle f$  remains unsolved "at the end", type inference fails.

But when is the end?

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How does  $\langle \alpha \rangle f$  interact with let-generalization?

### Practical difficulty: generalization (2/2)

Generalization: which inference variables  $\alpha$  are *local* and and can be generalized into polymorphic variables?

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```
Frozen generalization of \tau:
```

- if a variable  $\beta$  of  $\tau$  is "blocked" by a frozen constraint,
- it must be tracked during instantiation and possibly generalized later.

#### Partially-frozen schemas:

- On generalization: store  $\beta$  as a blocked schema variable.
- On instantiation: track the instance of the partially-frozen schema.
- When  $\beta$  gets unblocked: continue generalization, update tracked instances.

Delicate to implement. Difficult to implement efficiently.

#### Theoretical difficulty: semantics (1/3)

Constraints are given meaning by a solution relation  $V \Vdash C$ .

A good constraint generator has correct solutions.

A good constraint solver (big-step function or small-step rewrites) preserves solutions.

$$\frac{\tau[V] =_{\mathsf{ty}} \tau'[V]}{V \Vdash \tau = \tau'} \qquad \qquad \frac{V \Vdash C[T/\alpha]}{(T, V) \Vdash \exists \alpha. C}$$

How to specify frozen constraints?

Theoretical difficulty: semantics (2/3)

Natural approach:

 $\frac{V \Vdash f(\alpha[V])}{V \Vdash \langle \alpha \rangle f}$ 

This specification allows "out of thin air" behaviors.

$$[\alpha \mapsto \mathsf{int}] \Vdash \langle \alpha \rangle (\lambda \tau. \, \alpha = \mathsf{int})$$

Our solver does not: the specification is not precise enough.

Theoretical difficulty: semantics (3/3)

We want to express that  $\alpha[V]$  is determined "without looking inside f ". How can we do this?

Morally:

$$\frac{C[\top] \text{ determines } \alpha \quad V \Vdash C[f(\alpha[V])]}{V \Vdash C[\langle \alpha \rangle f]}$$

#### Summary

Frozen constraints: interesting but difficult constraint combinator.

Work in progress.

Thanks! Questions?